

# MIP reformulations of some chance-constrained mathematical programs

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joint work with Ahmad Abdi



# Outline

## 1 Introduction

## 2 Our results

- Characterizing valid inequalities
- Separation over a large class of inequalities
- Explicit facet-defining inequalities
- Extended formulation

## 3 Conclusion

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  - ▶ **Chance-constrained program: Want a high probability of satisfying set of constraints**

## Chance-constrained programs

Chanced-constrained linear programming problem with stochastic right-hand sides:

$$\begin{aligned} \text{(PLP)} \quad & \min \quad c^T x \\ & \text{s.t.} \quad \mathbb{P}(Tx \geq \xi) \geq 1 - \epsilon \\ & \quad \quad x \in X, \end{aligned}$$

- $X \subset \mathbb{R}^d$ : a polyhedron,
- $\xi$ : random variable in  $\mathbb{R}^m$  with finite discrete distribution,
- $T \in \mathbb{R}^{m \times d}$ ,
- $\epsilon \in (0, 1)$ , and
- $c \in \mathbb{R}^n$ .

Suppose that  $\xi$  takes values from  $\xi^1, \dots, \xi^n$  with probabilities  $\pi_1, \dots, \pi_n$ , respectively.

## Feasibility: Example

Consider the special case where  $d = m = 3$ ,  $n = 4$ ,  $c = (1, 1, 1)$ ,  $X = \mathbb{R}^d$ ,  $T = I$ ,  $\epsilon = 0.5$ ,  $\pi = (0.25, 0.25, 0.25, 0.25)$ .

$$\text{Let } \{\xi^j\}_{j=1}^n = \left\{ \begin{pmatrix} 4 \\ 5 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 8 \\ 4 \end{pmatrix}, \begin{pmatrix} 7 \\ 1 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ 5 \\ 1 \end{pmatrix} \right\}$$

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Then  $x$  is feasible if and only if  $x \geq \xi^j$  for at least two  $j \in \{1, \dots, 4\}$ .

So to get a feasible solution, one needs to pick any two out of 4 scenarios to be satisfied.

Thus

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & \mathbb{P}(Tx \geq \xi) \geq 1 - \epsilon \Rightarrow \\ & x \in X, \end{aligned} \quad \Rightarrow \quad \begin{aligned} \min \quad & \sum_{i=1}^m \max_{j \in I} \xi_i^j \\ \text{s.t.} \quad & I \subseteq \{1, \dots, n\}, |I| \geq 2 \end{aligned}$$

$$\begin{aligned} \min \quad & \sum_{i=1}^m \max_{j \in I} \xi_i^j \\ \text{s.t.} \quad & I \subseteq \{1, \dots, n\}, |I| \geq K \end{aligned}$$

**NP-complete problem** CLIQUE: Given  $G = (V, E)$ , is there a clique of size at least  $C$ ?

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- Vertices to constraints
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is the cardinality of the smallest set of vertices covering at least  $K$  edges of  $G$ .

## NP-hardness [Luedtke, Ahmed and Nemhauser, 2010]

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So if there is a clique of size  $C$  ( $C - 1)/2$ , then there is a solution to such problem with  $K = C(C - 1)/2$  and objective  $\leq C$  (and vice-versa). □

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- Nonetheless, the discrete distribution case with Monte-Carlo sampling and using as confidence parameter  $\alpha > \epsilon$  gives us a lower bound on the optimal solution with probability  $1 - \exp\{-2n(\alpha - \epsilon)^2\}$  (Luedtke et al, 2010).

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- Under some mild assumptions (like continuity), the discrete distribution case with Monte-Carlo sampling and using as confidence parameter  $\alpha < \epsilon$  gives us a feasible solution with probability approaching 1 exponentially with  $n$  (Luedtke et al, 2010).

## Previous work on Chance-constrained programs

- Charnes et al. (1958) - Chance-constrained programs with disjoint probabilistic constraints
- Miller and Wagner (1965) - Chance-constrained programs with joint probabilistic constraints for independent random variables.
- Prékopa (1970) - Log-concave probability measure on random right-hand sides: There is an equivalent convex program
- Sen (1992) - Chance-constrained programs with discrete distributions using disjunctive programming reformulation.
- Ruszczyński (2002) - Precedence-constrained knapsack set: Use scenarios that dominate others.
- Luedtke, Ahmed and Nemhauser (2010) and Küçükyavuz (2012) - Chance-constrained programs with discrete random variables in the right-hand-side: MIP reformulation
- Our work: Extends Luedtke et al. (2010) and Küçükyavuz (2012)

## MIP reformulation [Luedtke, Ahmed and Nemhauser, 2010]

Let  $z \in \{0, 1\}^n$  where  $z_j = 0$  guarantees that  $Tx \geq \xi_j$ . Then (PLP) is equivalent to

$$\begin{aligned} \text{(PLP)} \quad & \min \quad c^T x \\ & \text{s.t.} \quad y = Tx \\ & \quad y + z_j \xi_j \geq \xi_j \quad \forall j \in [n] \\ & \quad \sum_{j=1}^n \pi_j z_j \leq \epsilon \\ & \quad z \in \{0, 1\}^n \\ & \quad x \in X. \end{aligned}$$

Let's look at a single chance-constraint: For each  $k \in [m]$ , let

$$\mathcal{D}_k := \left\{ (y_k, z) \in \mathbb{R}_+ \times \{0, 1\}^n : \sum_{j=1}^n \pi_j z_j \leq \epsilon, y_k + \xi_{jk} z_j \geq \xi_{jk} \quad \forall j \in [n] \right\}.$$

### Goal

Study  $\mathcal{D}_k$  and get cuts to strengthen the MIP formulation

Changing notation a bit:

$$\mathcal{Q} := \left\{ (y, z) \in \mathbb{R}_+ \times \{0, 1\}^n : \sum_{j \in [n]} a_j z_j \leq p, y + h_j z_j \geq h_j \quad \forall j \in [n] \right\}.$$

## Other related work

Mixing set with a knapsack constraint:

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- Work on the mixing set:
  - ▶ Günlük and Pochet
  - ▶ Zhao and de Farias,
  - ▶ Conforti, di Summa and Wolsey
  - ▶ Miller and Wolsey
  - ▶ van Vyve
  - ▶ to mention a few
- Qiu, Ahmed, Dey, Wolsey - Cover LPs with violation
- J. Luedtke, S. Küçükyavuz, Y. Song, A Branch-and-Cut Algorithm for the Chance-Constrained Knapsack Problem.
- S. Küçükyavuz, M. Zhang, On Continuous Mixing Set with a Cardinality Constraint.

# Cutting plane approach

Mixed Integer Programming (MIP):

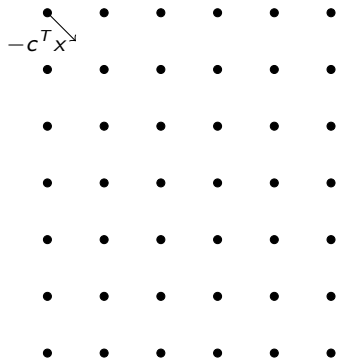
$$\begin{array}{ll} \min & c^T x \\ \text{s.t.} & Ax \leq b \\ & x \in \mathbb{Z}^p \times \mathbb{R}^{n-p} \end{array}$$

- 1 Let  $P_I$  be the set of feasible solutions to our MIP.
- 2 Let  $R$  be a relaxation of  $P_I$  (typically by dropping integrality constraints), that is  $R \supseteq P_I$ .
- 3 Solve the optimization problem over  $R$ , with optimal solution  $x^* \in R$
- 4 Find a **cut/cutting plane/valid inequality**: An inequality  $\pi^T x \leq \pi_o$  satisfied by all  $x \in P_I$ , but with  $\pi^T x^* > \pi_o$
- 5 Let  $R \leftarrow R \cap \{x : \pi^T x \leq \pi_o\}$
- 6 Go to 3

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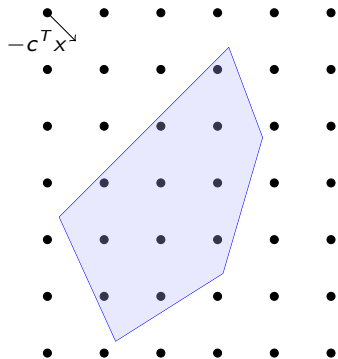
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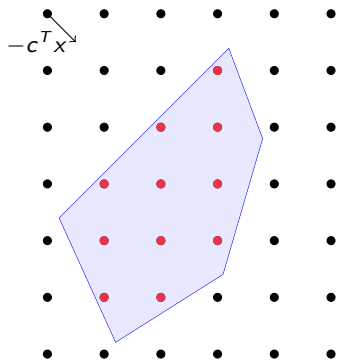




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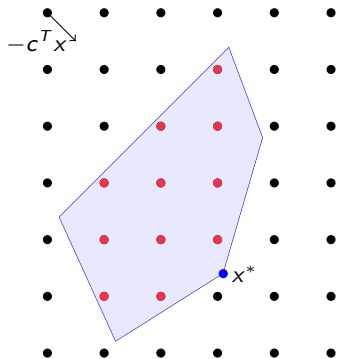
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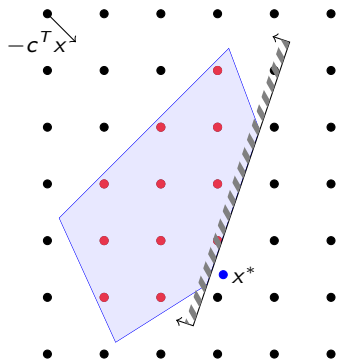


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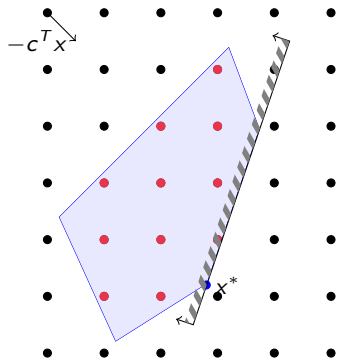


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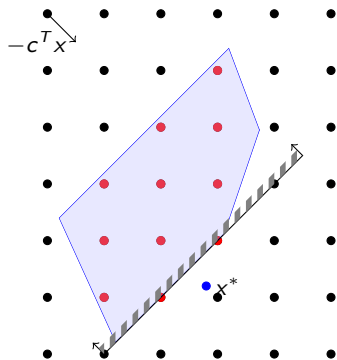


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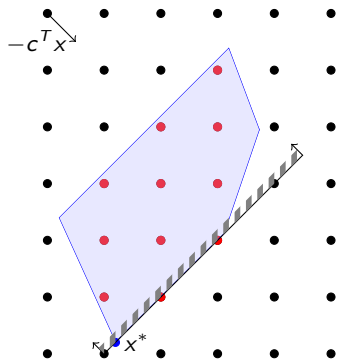


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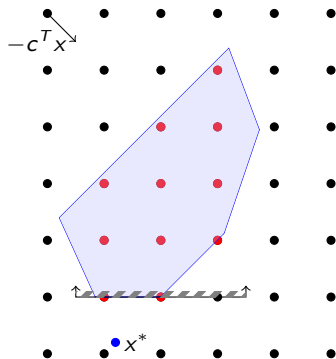


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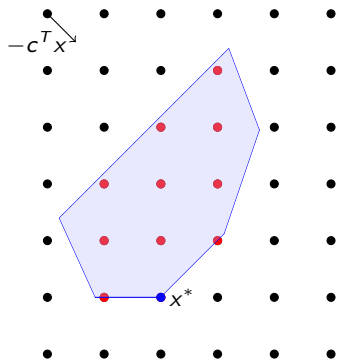


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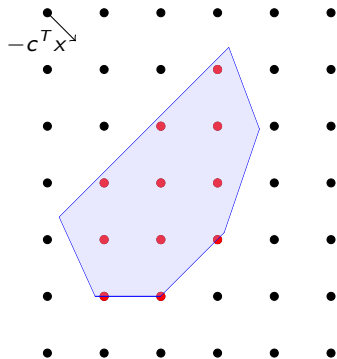
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Valid inequalities/  
Cutting planes/  
Cuts



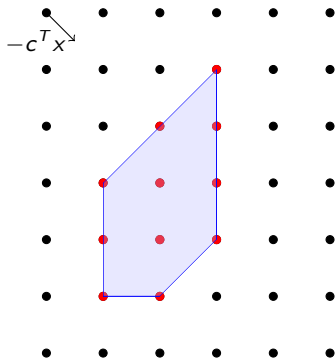
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$$\begin{array}{ll} \min & c^T x \\ \text{s.t.} & Ax \leq b \end{array}$$

$$\begin{array}{l} \pi^1 x \leq \pi_o^1 \\ \pi^2 x \leq \pi_o^2 \\ \pi^3 x \leq \pi_o^3 \end{array}$$

Valid inequalities/  
Cutting planes/  
Cuts



Want "strongest possible" valid inequalities (facet-defining): Get the convex hull of feasible solutions

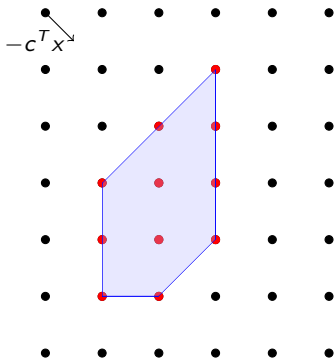
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Want "strongest possible" valid inequalities (facet-defining): Get the convex hull of feasible solutions

OBS: A strong formulation may be obtained implicitly, for instance as a projection of a higher dimensional polyhedron (**Extended formulation**).

## Mixing set with a knapsack constraint

Luedtke et al. (2010) and Küçükyavuz (2012) study inequalities for

$$\mathcal{Q} := \left\{ (y, z) \in \mathbb{R}_+ \times \{0, 1\}^n : \sum_{j \in [n]} a_j z_j \leq p, y + h_j z_j \geq h_j \quad \forall j \in [n] \right\}.$$

- For the cardinality constraint/equal probabilities case (all  $a_j = 1$ ):
  - ▶ Characterization of all valid inequalities and separation (Luedtke et al.)
  - ▶ Extended formulation (Luedtke et al.)
  - ▶  $(T, \Pi_L)$  inequalities (Küçükyavuz)
  - ▶ Compact extended formulation (Küçükyavuz)
- For the general constraint/probabilities case:
  - ▶ Strengthened star inequalities (Luedtke et al.)
  - ▶ Extended formulation for LP+strengthen star (Luedtke et al.)
  - ▶ Strengthened  $(T, \Pi_L)$  inequalities (Küçükyavuz)

# Mixing set with a knapsack constraint

Experiments by Küçükyavuz:

**Table 2** Probabilistic lot-sizing experiments

$f$	$r$	Gap			Gapimp			Cuts			Nodes			Time (endgap)		
		CPX	Mix	TL	CPX	Mix	TL	CPX	Mix	TL	CPX	Mix	TL	CPX	Mix	TL
0	5	1.3	23	90	90	85	559	199	1,139	117	81	130	255	59		
	10	1.7	26	97	97	131	833	333	10,493	171	68	821	529	104		
	15	2.0	24	98	98	217	1360	559	36,765	265	209	T(0.4)	1,387	341		
	20	2.4	18	97	97	248	1,527	779	25479.0	291	418	T(1.0)	1,764	967		
1	5	2.4	47	74	74	235	574	359	72,889	3,258	15,663	T(0.3)	T(0.4)	3,476 (0.2)		
	10	2.7	43	78	77	288	846	499	39,773	1,323	4,169	T(0.7)	T(0.5)	T(0.4)		
	15	3.1	39	77	76	373	1,334	707	22,837	492	1,831	T(1.4)	T(0.7)	T(0.6)		
	20	3.5	36	75	76	452	1,849	1,089	17,031	245	939	T(1.7)	T(0.9)	T(0.7)		

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**Our goal: Extend their results**

# Outline

## 1 Introduction

## 2 Our results

- Characterizing valid inequalities
- Separation over a large class of inequalities
- Explicit facet-defining inequalities
- Extended formulation

## 3 Conclusion

## Valid inequalities for $Q$

### Lemma

Suppose that

$$\gamma y + \sum_{j \in [n]} \alpha_j z_j \geq \beta \quad (1)$$

is a valid inequality for  $\text{conv}(Q)$  for some  $\alpha \in \mathbb{R}^n, \gamma, \beta \in \mathbb{R}$ . Then  $\gamma \geq 0$ . Moreover, if  $\gamma = 0$  then (1) is a valid inequality for  $\mathcal{P} := \{z \in \{0, 1\}^n : \sum_{j=1}^n a_j z_j \leq p\}$ .

### Proof.

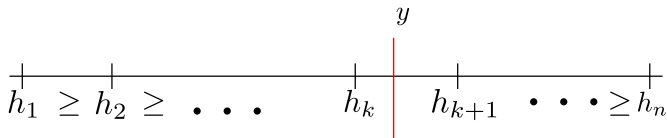
Observe that  $(1, 0) \in \text{rcone}(\text{conv}(Q))$ . This implies that  $\gamma \geq 0$ . Moreover, since  $\text{conv}(\mathcal{P}) = \text{proj}_z(\text{conv}(Q))$ , it follows that if  $\gamma = 0$  then (1) is a valid inequality for  $\text{conv}(\mathcal{P})$ . □



## A few observations

$$\mathcal{Q} := \left\{ (y, z) \in \mathbb{R}_+ \times \{0, 1\}^n : \sum_{j \in [n]} a_j z_j \leq p, y + h_j z_j \geq h_j \quad \forall j \in [n] \right\}.$$

- We may assume, WLOG that  $h_1 \geq h_2 \geq \dots \geq h_n$ .
- Let  $\nu := \max\{k : \sum_{j \leq k} a_j \leq p\}$ .
- If  $h_k > y \geq h_{k+1}$ , then  $z_j = 1$  for all  $j \leq k$
- Therefore,  $y \geq h_{\nu+1}$



## Inequalities that do not come from $\mathcal{P}$

Previous Lemma implies we may assume have the form:

$$y + \sum_{j \in [n]} \alpha_j z_j \geq \beta$$

Define, for each  $0 \leq k \leq \nu$ , the knapsack set

$$\mathcal{P}_k := \left\{ z \in \{0, 1\}^{[n]} : \sum_{j > k} a_j z_j \leq p - \sum_{j \leq k} a_j \right\}.$$

### Theorem (Abdi and F.)

$y + \sum_{j \in [n]} \alpha_j z_j \geq \beta$  is a valid inequality for  $\text{conv}(\mathcal{Q})$  if and only if  $(\alpha, \beta) \in \mathcal{G}$ , where

$$\mathcal{G} := \left\{ (\alpha, \beta) \in \mathbb{R}^n \times \mathbb{R} : \sum_{j \leq k} \alpha_j + \sum_{j > k} \alpha_j z_j^* + h_{k+1} \geq \beta, \forall z^* \in \mathcal{P}_k, \forall 0 \leq k \leq \nu. \right\}$$

## Rewriting $\mathcal{G}$

$$\mathcal{G} := \left\{ (\alpha, \beta) \in \mathbb{R}^n \times \mathbb{R} : \sum_{j \leq k} \alpha_j + \sum_{j > k} \alpha_j z_j^* + h_{k+1} \geq \beta, \forall z^* \in \mathcal{P}_k, \forall 0 \leq k \leq \nu. \right\}$$

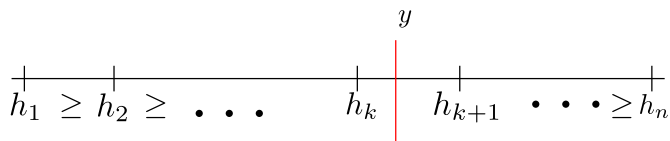
Let

$$f_k(\alpha) := \min \left\{ \sum_{j > k} \alpha_j z_j : z \in \mathcal{P}_k \right\}. \quad (2)$$

Then it is easy to see that

$$\mathcal{G} = \left\{ (\alpha, \beta) \in \mathbb{R}^n \times \mathbb{R} : \sum_{j \leq k} \alpha_j + f_k(\alpha) + h_{k+1} \geq \beta, \forall 0 \leq k \leq \nu \right\}.$$

# Proof



Recall:

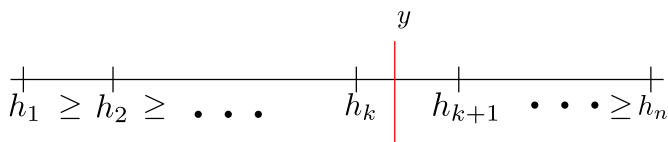
$z_j = 1$  for all  $j \leq k$

( $\Leftarrow$ ) Let  $(y^*, z^*) \in \mathcal{Q}$ . Let  $h_0 := +\infty$ .

Then  $h_k > y^* \geq h_{k+1}$  for some  $0 \leq k \leq \nu$ . Since  $z_j^* = 1$  for all  $j \leq k$ ,  $z^* \in \mathcal{P}_k$ . Then

$$\begin{aligned} y^* + \sum_{j \in [n]} \alpha_j z_j^* &\geq h_{k+1} + \sum_{j \leq k} \alpha_j + \sum_{j > k} \alpha_j z_j^* \\ &\geq h_{k+1} + \sum_{j \leq k} \alpha_j + f_k(\alpha) \\ &\geq \beta \quad \text{since } (\alpha, \beta) \in \mathcal{G} \end{aligned}$$

## Proof



Recall:

$z_j = 1$  for all  $j \leq k$

( $\Rightarrow$ ) Take  $0 \leq k \leq \nu$ . Let  $z^* \in \{0, 1\}^n$  be an optimal solution to  $f_k(\alpha)$  with  $z_j^* = 1$  for all  $1 \leq j \leq k$ . Let  $y^* = h_{k+1}$ . Observe that  $(y^*, z^*) \in \mathcal{Q}$ . Hence, validity implies that

$$\begin{aligned}\beta &\leq y^* + \sum_{j \in [n]} \alpha_j z_j^* \\ &= h_{k+1} + \sum_{j \leq k} \alpha_j + \sum_{j > k} \alpha_j z_j^* \\ &= h_{k+1} + \sum_{j \leq k} \alpha_j + f_k(\alpha).\end{aligned}$$

Since this holds for all  $0 \leq k \leq \nu$ , it follows that  $(\alpha, \beta) \in \mathcal{G}$ .

## A few observations

- This theorem implies that separation over inequalities of this form can be done in polytime if optimization over  $\mathcal{P}$  can be solved in polytime

$$f_k(\alpha) := \min \left\{ \sum_{j>k} \alpha_j z_j : z \in \mathcal{P}_k \right\}.$$

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- Note that if  $\alpha \geq 0$ ,  $f_k(\alpha)$  can be solved easily for all  $k$
- Complexity of separation “resides” in negative coefficients.

$$f_k(\alpha) := \min \left\{ \sum_{j>k} \alpha_j z_j : z \in \mathcal{P}_k \right\}.$$

## Separation over a large class of inequalities

Let  $R, S$  be a partition of  $[n]$ . Let's assume that  $j \in R$  implies  $\alpha_j \geq 0$ . Then any inequality of the form

$$y + \sum_{j \in [n]} \alpha_j z_j \geq \beta$$

with  $\alpha_j \geq 0$ , for all  $j \in R$  is in  $\mathcal{G} \cap \{\alpha_j \geq 0, \forall j \in R\}$

### Theorem (Abdi and F.)

*If optimization over  $\{z \in \{0, 1\}^S : \sum_{j \in S} a_j z_j \leq p\}$  can be done in polynomial time, then separation over all valid inequalities  $y + \sum_{j \in [n]} \alpha_j z_j \geq \beta$  such that  $\alpha_j \geq 0, \forall j \in R = [n] \setminus S$  can be done in polynomial-time.*

Examples:

- $a_j$  not too large for  $j \in S$
- All  $a_j$  equal for  $j \in S$  (in this case, a better characterization is possible)

## Theorem (Abdi and F.)

Consider an inequality of the form

$$y + \sum_{j \in [n]} \alpha_j z_j \geq \beta. \quad (3)$$

If there exists  $(\sigma, \rho) \in \mathbb{R}_-^{\nu+1} \times \mathbb{R}_-^{(\nu+1)(n-\nu/2)}$  such that  $(\alpha, \beta, \sigma, \rho) \in \mathcal{J}$ , then (3) is a valid inequality for  $\text{conv}(\mathcal{Q})$ . Furthermore, when  $a_i = 1$  for all  $i \in S \subseteq [n]$  and (3) is a valid inequality for  $\text{conv}(\mathcal{Q})$  with  $\alpha_j \geq 0, \forall j \in R := [n] \setminus S$ , then there exists  $(\sigma, \rho) \in \mathbb{R}_-^{\nu+1} \times \mathbb{R}_-^{(\nu+1)(n-\nu/2)}$  such that  $(\alpha, \beta, \sigma, \rho) \in \mathcal{J}$ , where

$$\mathcal{J} := \left\{ (\alpha, \beta, \sigma, \rho) : \begin{array}{ll} \sum_{j \leq k} \alpha_j + \beta_k \sigma_k + \sum_{j > k} \rho_{kj} + h_{k+1} \geq \beta & \forall 0 \leq k \leq \nu, \\ a_j \sigma_k + \rho_{kj} \leq \alpha_j & \forall n \geq j > k \\ \sigma, \rho \leq 0, \alpha_j \geq 0, \forall j \in R & \forall 0 \leq k \leq \nu. \end{array} \right\}$$

## Proof idea

We saw that the set of valid inequalities is characterized by

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Use such characterization and LP duality to obtain the formulation.

## Properties of facet-defining inequalities for $\text{conv}(\mathcal{Q})$

### Lemma (Abdi and F.)

Suppose that the inequality

$$y + \sum_{j \in [n]} \alpha_j z_j \geq \beta \quad (4)$$

is facet-defining for  $\text{conv}(\mathcal{Q})$ . Then

- (i)  $(\alpha, \beta)$  is an extreme point of  $\mathcal{G}$ ,
- (ii)  $\beta = h_1 + f_0(\alpha)$ , and
- (iii) if  $\alpha_k < 0$  for some  $1 \leq k \leq n$ , then  $a_k > 0$ .

Note:  $f_0(\alpha) := \min \left\{ \sum_{j \in [n]} \alpha_j z_j : \sum_{j \in [n]} a_j z_j \leq p \right\}$

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- Consider the cardinality constrained case ( $a_j = 1, \forall j$ ).



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- Suppose  $|S| \leq p$
- Then  $f_0(\alpha) := \min \left\{ \sum_{j \in [n]} \alpha_j z_j : \sum_{j \in [n]} a_j z_j \leq p \right\} = \sum_{j \in S} \alpha_j$ , hence any such facet-defining inequality will have the form:

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$$y + \sum_{j \in R} \alpha_j z_j + \sum_{j \in S} \alpha_j z_j \geq h_1 + \sum_{j \in S} \alpha_j$$

$$y + \sum_{j \in R} \alpha_j z_j + \sum_{j \in S} \Delta_j (1 - z_j) \geq h_1$$

with  $\alpha, \Delta \geq 0$

## Luedtke et al.'s inequalities

Luedtke et al.'s inequalities for the cardinality constrained case:

### Theorem (Luedtke et al.)

Let  $m \in \{1, \dots, p\}$ ,  $R = \{r_1, \dots, r_a\} \subseteq \{1, \dots, m\}$  and  $S = \{q_1, \dots, q_{p-m}\} \subseteq \{p+1, \dots, n\}$ . For  $m < p$ , define  $\Delta_1^m = h_{m+1} - h_{m+2}$  and

$$\Delta_i^m = \max \left\{ \Delta_{i-1}^m, h_{m+1} - h_{m+i+1} - \sum_{j=1}^{i-1} \Delta_j^m \right\}, i = 2, \dots, p-m$$

Then, with  $h_{r_{a+1}} = h_{m+1}$ ,

$$y + \sum_{j=1}^a (h_{r_j} - h_{r_{j+1}}) z_{r_j} + \sum_{j=1}^{p-m} \Delta_j^m (1 - z_{q_j}) \geq h_{r_1}$$

is valid for  $Q$  and facet-defining if  $h_{r_1} = h_1$

## Validity proof

Note:  $0 \leq \Delta_1^m \leq \Delta_2^m \leq \dots \leq \Delta_{p-m}^m$

$$\mathcal{G} := \left\{ (\alpha, \beta) \in \mathbb{R}^n \times \mathbb{R} : \sum_{j \leq k} \alpha_j + f_k(\alpha) + h_{k+1} \geq \beta, \forall 0 \leq k \leq \nu. \right\}$$

In this case,  $\nu = p$ . Note that  $S \subseteq \{p+1, \dots, n\}$ , so  $j \in S \Rightarrow j > \nu = p$ .

$$f_k(\alpha) := \min \left\{ \sum_{j > k} \alpha_j z_j : z \in \mathcal{P}_k \right\}$$

$$f_k(\alpha) := \min \left\{ \sum_{j \in S} -\Delta_j^m z_j : \sum_{j \in S} z_j \leq p - k \right\} = - \sum_{j=k-m+1}^{p-m} \Delta_j^m$$

$$\sum_{j \leq k} \alpha_j + f_k(\alpha) + h_{k+1} \geq \beta$$

becomes

$$\sum_{j \leq k: j \in R} \alpha_j - \sum_{j=k-m+1}^{p-m} \Delta_j^m + h_{k+1} \geq h_1 - \sum_{j \in S} \Delta_j^m \iff$$

$$\sum_{j \leq k: j \in R} \alpha_j + \sum_{j=1}^{k-m} \Delta_j^m + h_{k+1} \geq h_1$$

Note that  $\sum_{j \leq k: j \in R} \alpha_j = h_1 - h_{r_t}$  for some  $r_t > k$ .

$$\sum_{j \leq k: j \in R} \alpha_j + \sum_{j=1}^{k-m} \Delta_j^m + h_{k+1} \geq h_1$$

So if  $k < m$

$$\sum_{j \leq k: j \in R} \alpha_j + \sum_{j=1}^{k-m} \Delta_j^m + h_{k+1} = h_1 - h_{r_t} + h_{k+1} \geq h_1$$

And if  $k \geq m$ ,  $\Delta_{k-m}^m \geq h_{m+1} - h_{m+k-m+1} - \sum_{j=1}^{k-m-1} \Delta_j^m$  so

$$\sum_{j \leq k: j \in R} \alpha_j + \sum_{j=1}^{k-m} \Delta_j^m + h_{k+1} \geq \sum_{j \in R} \alpha_j + h_{m+1} - h_{k+1} + h_{k+1} = h_1 - h_{r_{a+1}} + h_{m+1} = h_1$$

## More inequalities for the cardinality constrained case

### Theorem (Küçükyavuz, 2012)

Suppose that  $a_j = 1$  for all  $j \in [n]$ . Take a positive integer  $m \leq \nu = p$ . Suppose that

- (i)  $R := \{r_1, \dots, r_a\} \subset \{1, \dots, m\}$ , where  $r_1 < \dots < r_a$ ; and
- (ii)  $S \subset \{m+2, \dots, n\}$  and take a permutation of the elements in  $S$ ,  $\Pi_S := \{q_1, \dots, q_{p-m}\}$  such that  $q_j > m+j$  for all  $1 \leq j \leq p-m$ .

Set  $r_{a+1} := m+1$ . Let  $\Delta_1 := h_{m+1} - h_{m+2}$ , and for  $2 \leq j \leq p-m$  define

$$\Delta_j := \max \left\{ \Delta_{j-1}, h_{m+1} - h_{m+1+j} - \sum (\Delta_i : q_i > m+j, i < j) \right\}.$$

Then the  $(T, \Pi_L)$  inequality

$$y + \sum_{j=1}^a (h_{r_j} - h_{r_{j+1}}) z_{r_j} + \sum_{j=1}^{p-m} \Delta_j (1 - z_{q_j}) \geq h_{r_1} \quad (5)$$

is valid for  $\text{conv}(\mathcal{Q})$ . Furthermore, (5) is facet-defining inequality for  $\text{conv}(\mathcal{Q})$  if and only if  $h_{r_1} = h_1$ .



## Theorem (Abdi and F.)

Take an integer  $0 \leq m \leq \nu$  such that  $p - s_m$  is an integer. For each  $1 \leq j \leq p - s_m$ , let  $k(j) := \max\{k : j \geq s_k - s_m\}$ . Let

- (i)  $R := \{r_1, \dots, r_a\} \subset \{1, \dots, m\}$  where  $r_1 < \dots < r_a$ ;
- (ii)  $S := \{q_1, \dots, q_s\} \subset \{m + 2, \dots, n\}$  where  $s = p - s_m$  and  $q_j > k(j)$  for all  $1 \leq j \leq p - s_m$ ; and
- (iii)  $S$  is chosen so that  $a_j = 1$  for all  $j \in S$ , and  $a_j \leq s_m$  for all  $j \notin S$ .

Set  $r_{a+1} = m + 1$ . Let  $\Delta_{q_1} := h_{m+1} - h_{k(1)+1}$ , and for  $2 \leq j \leq p - s_m$ , define

$$\Delta_{q_j} := \max \left\{ \Delta_{q_{j-1}}, h_{m+1} - h_{k(j)+1} + \sum (\Delta_{q_i} : q_i > k(j), i < j) \right\}. \quad (6)$$

Then

$$y + \sum_{j=1}^a (h_{r_j} - h_{r_{j+1}})z_{r_j} + \sum_{i \in S} \Delta_i(1 - z_i) \geq h_{r_1} \quad (7)$$

is a valid inequality for  $\text{conv}(\mathcal{Q})$ . Furthermore, (7) is a facet-defining inequality for  $\text{conv}(\mathcal{Q})$  if and only if  $h_{r_1} = h_1$ .

## Extended formulation

Küçükyavuz (2012):

- If  $(y^*, z^*)$  is an extreme point of  $\text{conv}(\mathcal{Q})$ , then  $y \in \{h_1, h_2, \dots, h_{\nu+1}\}$ .
- For each  $0 \leq k \leq \nu$ , let

$$\mathcal{Q}_{k+1} := \left\{ (y, z) \in \{h_{k+1}\} \times \{0, 1\}^n : \sum_{j \in [n]} a_j z_j \leq p, z_j \geq 1 \forall j \leq k \right\}.$$

$$\mathcal{R}_{k+1} := \left\{ (y, z) \in \{h_{k+1}\} \times [0, 1]^n : \sum_{j \in [n]} a_j z_j \leq p, z_j \geq 1 \forall j \leq k \right\}.$$

- $\text{conv}(\mathcal{Q}) = \text{conv}(\bigcup_{k=1}^{\nu+1} \mathcal{Q}_k) + \mathcal{C} \subseteq \text{conv}(\bigcup_{k=1}^{\nu+1} \mathcal{R}_k) + \mathcal{C}$
- This leads to a polynomial-size extended formulation that is exact in the cardinality constraint case.

## Extended formulation

Küçükyavuz (2012):

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- This leads to a polynomial-size extended formulation that is exact in the cardinality constraint case.
- How strong is such extended formulation in the general case?

## Extended formulation

### Theorem (Abdi and F.)

Let  $EQ$  be the extended formulation obtained as described. Then

$$\text{proj}_{y,z}(EQ) \subseteq \left\{ (y, z) \in \mathbb{R}_+ \times [0, 1]^n : \begin{array}{l} y + h_j z_j \geq h_j \quad , \forall j = 1, \dots, n \\ \sum_{j=1}^n a_j z_j \leq p \\ y + \sum_{j=1}^n \alpha_j z_j \geq \beta \quad , \forall (\alpha, \beta) \in \mathcal{G}_1 \end{array} \right\}$$

where  $\mathcal{G}_1$  is the set of coefficients of valid inequalities that are only allowed to have negative coefficients for all  $j$  such that  $a_j = 1$ .

Note: Using similar arguments, one can derive polynomial size extended formulations which have even better provable strength.

## A better extended formulation

Bienstock (2008) gave polynomial-size formulations that have arbitrarily close gap to the convex hull of 0-1 solutions to the knapsack set.

Can we use his results in this context?

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### Theorem (Abdi and F.)

For any  $M > 0$  and  $\epsilon > 0$  there exists a polyhedron  $\mathcal{RQ}$  such that  $\text{conv}(Q) \subset \mathcal{RQ}$ , and if  $(y^*, z^*) \in \mathcal{RQ}$  and  $y + \sum_{j=1}^n \alpha_j z_j \geq \beta$  is a valid inequality of  $\text{conv}(Q)$  whose coefficients,  $\alpha_j$ , are bounded below by  $-M$ , then

$$y^* + \sum_{j=1}^n \alpha_j z_j^* \geq \beta - \epsilon Mn.$$

Moreover,  $\mathcal{RQ}$  can be described explicitly as the projection of a polyhedron of dimension  $O(\epsilon^{-1} n^{1+\lceil 1/\epsilon \rceil})$  that is described by  $O(\epsilon^{-1} n^{2+\lceil 1/\epsilon \rceil})$  constraints.

# Computational experiments



## Computational experiments



# Outline

## 1 Introduction

## 2 Our results

- Characterizing valid inequalities
- Separation over a large class of inequalities
- Explicit facet-defining inequalities
- Extended formulation

## 3 Conclusion

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Take away:

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Take away: **Try to reduce the complexity of the negative part!**

"The important thing is to realize the positive side  
and try to increase that; realize the negative side  
and try to reduce.  
That's the way."

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THANK YOU!