Optimal Stock Selling Based on the Global Maximum

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 6^{th} World Congress of the Bachelier Finance Society, June 22-26, \$2010\$

(joint work with Dr. M. Dai and Z. Yang)

If I were an Innocent Investor...

- I just bought a stock and must sell it in one year
- Need to decide when to sell?
- Obviously, sell it at the maximum price of the whole year.
 However, this is an impossible mission.
- So, what about selling at the price "closest" to the maximum?

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This talk is using square error to measure "closeness" and studying the optimal selling strategy under this criterion.

The Model

- A Black-Scholes market with one stock and one saving account
- The *discounted* stock price follows, on $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \ge 0}, P)$,

$$dS_t = \mu S_t dt + \sigma S_t dW_t,$$

where $\mu \in (-\infty,\infty)$ and $\sigma > 0$ are constants

Let M_s = max_{0≤t≤s} S_t, 0 ≤ s ≤ T be the running maximum of stock price

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- ▶ Let $M_s = \max_{0 \le t \le s} S_t, 0 \le s \le T$ be the running maximum of stock price
- Consider the following optimal stopping problem

$$\inf_{0 \le \nu \le T} \mathbb{E}[(S_{\nu} - M_T)^2],$$

where \mathbb{E} stands for the expectation, ν is an \mathcal{F}_t -stopping time.

Related (Probabilistic) Literature

 Graversen, Peskir and Shiryaev (2000), Theory Prob Appl, studied

$$\inf_{0 \le \nu \le T} \mathbb{E}[(S_{\nu}^{0} - M_{T}^{0})^{2}],$$

where $S_t^0 = W_t$, $M_T^0 = \max_{0 \le t \le T} W_t$ and obtained explicit optimal solution

$$\nu * = \inf\{t : M_t^0 - S_t^0 \ge z^* \sqrt{T - t}\}, z^* = 1.12\dots$$

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du Toit and Peskir (2007), Ann Prob, considered

$$\inf_{0 \le \nu \le T} \mathbb{E}[(S^{\mu}_{\nu} - M^{\mu}_T)^2],$$

where $\mu \neq 0$.

Related (Financial) Literature

Shiryaev, Xu and Zhou (2008), Quant Fin, studied the relative error between the selling price and global maximum,

$$\inf_{0 \le \nu \le T} \mathbb{E}\left[\frac{S_{\nu}}{M_T}\right]$$

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- "Bang-bang" strategy:
 - Sell at time $T: \mu > \frac{\sigma^2}{2}$ Sell at time $0: \mu \le \frac{\sigma^2}{2}$

PDE Formulation

The problem is

$$\inf_{0 \le \nu \le T} \mathbb{E}[(S_{\nu} - M_T)^2]$$

- Not a standard optimal stopping problem, since M_T is not *F_t*-adapted
- One more step:

$$\inf_{0 \le \nu \le T} \mathbb{E}[(S_{\nu} - M_T)^2] = \inf_{0 \le \nu \le T} \mathbb{E}\Big\{\mathbb{E}[(S_{\nu} - M_T)^2 \mid \mathcal{F}_{\nu}]\Big\}$$
$$= \inf_{0 \le \nu \le T} \mathbb{E}\Big\{\phi(\nu, S_{\nu}, M_{\nu})\Big\},$$

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where $\phi(t, S_t, M_t) = \mathbb{E}[(S_t - M_T)^2 \mid \mathcal{F}_t]$

PDE Formulation (Con't)

Denote the value function

$$\psi(t, S_t, M_t) = \inf_{t \le \nu \le T} \mathbb{E} \Big\{ \phi(\nu, S_\nu, M_\nu) \mid \mathcal{F}_t \Big\}$$

Dynamic programming equation (Variational Inequalities)

$$\begin{cases} \max\{-\partial_t \psi - \mathcal{L}^0 \psi, \psi - \phi\} = 0, & (t, S, M) \in D, \\ \partial_M \psi(t, M, M) = 0, & \psi(T, S, M) = (S - M)^2, \end{cases}$$

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where $\mathcal{L}^0 = \frac{\sigma^2}{2} \partial_{SS} + \mu \partial_S$ and $D = \{(t, S, M) : 0 < S < M, \ 0 \le t < T\}.$

The Obstacle Function $\phi(t, S, M)$

Recall

$$\begin{aligned} \phi(t, S_t, M_t) &= \mathbb{E}[(S_t - M_T)^2 \mid \mathcal{F}_t] \\ &= S_t^2 - 2S_t \mathbb{E}[M_T \mid \mathcal{F}_t] + \mathbb{E}[M_T^2 \mid \mathcal{F}_t] \\ &=: S_t^2 - 2S_t \phi_1(t, S_t, M_t) + \phi_2(t, S_t, M_t), \end{aligned}$$

where $\phi_i(t, S_t, M_t) = \mathbb{E}[M_T^i \mid \mathcal{F}_t].$

• Then, $\phi_i(t, S, M)$ satisfies

$$\begin{cases} -\partial_t \phi_i - \mathcal{L}^0 \phi_i = 0, & (t, S, M) \in D, \\ \partial_M \phi_i(t, M, M) = 0, & \phi_i(T, S, M) = M^i. \end{cases}$$

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Change of Variables

► Denote
$$\tau = T - t$$
, $x = \ln \frac{M}{S}$, $u_i(\tau, x) = \frac{\phi_i(t, S, M)}{S^i}$, $u(\tau, x) = \frac{\phi(t, S, M)}{S^2}$.

$$\begin{array}{l} \bullet \quad \text{Then, } u_1 \text{ and } u_2 \text{ satisfy} \\ \left\{ \begin{array}{l} \partial_\tau u_1 - \mathcal{L}_x^1 u_1 = 0 \quad \text{in } \Omega, \\ \partial_x u_1(\tau, 0) = 0, \ u_1(0, x) = e^x, \end{array} \right. \left\{ \begin{array}{l} \partial_\tau u_2 - \mathcal{L}_x^2 u_2 = 0 \quad \text{in } \Omega, \\ \partial_x u_2(\tau, 0) = 0, \ u_2(0, x) = e^{2x}, \end{array} \right. \end{array} \right.$$

where
$$\mathcal{L}_x^1 = \frac{\sigma^2}{2} \partial_{xx} - \left(\mu + \frac{\sigma^2}{2}\right) \partial_x + \mu$$
,
 $\mathcal{L}_x^2 = \frac{\sigma^2}{2} \partial_{xx} - \left(\mu + \frac{3\sigma^2}{2}\right) \partial_x + (2\mu + \sigma^2)$,
 $\Omega = (0, T] \times (0, \infty)$.

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Change of Variables (con't)

• Denote
$$v(\tau, x) = \frac{\psi(t, S, M) - \phi(t, S, M)}{S^2}$$

Then, v satisfies

$$\begin{cases} \max\left\{\partial_{\tau}v - \mathcal{L}_{x}^{2}v - H, v\right\} = 0 \text{ in } \Omega, \\ \partial_{x}v(\tau, 0) = 0, \ v(0, x) = 0, \end{cases}$$

where
$$H = \mathcal{L}_x^2 u - \partial_\tau u = 2\mu + \sigma^2 + 2\left(\sigma^2 \partial_x u_1 - (\mu + \sigma^2)u_1\right),$$

$$\mathcal{L}_x^2 = \frac{\sigma^2}{2} \partial_{xx} - \left(\mu + \frac{3\sigma^2}{2}\right) \partial_x + (2\mu + \sigma^2).$$

Define the selling region (the stopping region) as follows:

$$SR=\{(\tau,x)\in[0,\infty)\times(0,T]:v(\tau,x)=0\}.$$

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The Optimal Selling Strategy: Good Stock($\mu > 0$)

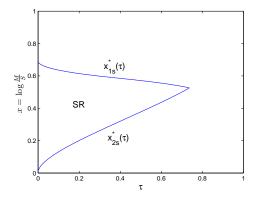


Figure: Two optimal selling boundaries. Parameter values used: $\mu = 0.045, \ \sigma = 0.3, \ T = 1.$

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The Optimal Selling Strategy: Bad Stock $(-\sigma^2 \le \mu \le 0)$

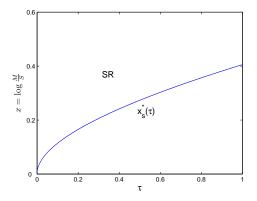


Figure: The monotonically increasing optimal selling boundary. Parameter values used: $\mu = -0.010$, $\sigma = 0.3$, T = 1.

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The Optimal Selling Strategy: Very Bad Stock ($\mu < -\sigma^2$)

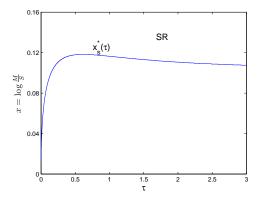


Figure: The nonmonotone optimal selling boundary. Parameter values used: $\mu = -0.032$, $\sigma = 0.4$, T = 3.

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The Proof

Recall

$$\begin{cases} \max\left\{\partial_{\tau}v - \mathcal{L}_{x}^{2}v - H, v\right\} = 0 \text{ in } \Omega, \\ \partial_{x}v(\tau, 0) = 0, \ v(0, x) = 0, \end{cases}$$

► So,

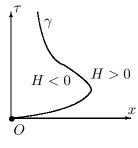
$$SR = \{(\tau, x) : v = 0\} \\ \subseteq \{(\tau, x) : \partial_{\tau} 0 - \mathcal{L}_x^2 0 - H \le 0\} \\ = \{(\tau, x) : H \ge 0\}$$

The Set $\{(\tau, x) : H \ge 0\}$

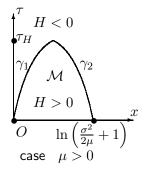
Lemma: Recall $H(\tau, x) = 2\mu + \sigma^2 + 2\left(\sigma^2 \partial_x u_1 - (\mu + \sigma^2)u_1\right)$.

• If
$$\mu \leq 0$$
, $\partial_x H > 0$;

- If $\mu \ge -\sigma^2$, $\partial_{\tau} H < 0$;
- If $\mu > 0$, $\partial_x H(\tau, x) = 0$ has at most one solution for any give $\tau > 0$;



case $\mu \leq 0$



With the help of previous lemma, we have

- $\partial_x v \ge 0$ if $\mu \le 0$;
- $\partial_{\tau} v \leq 0$ if $\mu \geq -\sigma^2$;
- These are due to

$$\partial_{\tau}v - \mathcal{L}_x^2 v = H, \text{in } \{(\tau, x) : v < 0\}.$$

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 $\blacktriangleright \text{ Define } x_s^*(\tau) = \inf\{x \in (0, +\infty) : v(\tau, x) = 0, \forall \tau \in (0, T]\}.$

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- Define $x_s^*(\tau) = \inf\{x \in (0, +\infty) : v(\tau, x) = 0, \forall \tau \in (0, T]\}.$
- Thanks to $\partial_x v \ge 0$, we can show

$$\begin{array}{lll} SR & = & \{(\tau, x) : v(\tau, x) = 0\} \\ & = & \{(\tau, x) : x \ge x^*_s(\tau), 0 < \tau \le T\}. \end{array}$$

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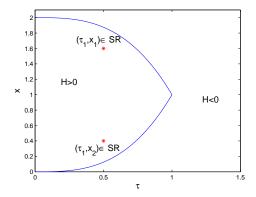
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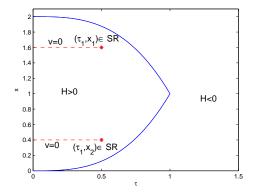
• $\partial_{\tau} v \leq 0$ gives the monotonicity of the free boundary.

• With $\mu > 0$, we have $\partial_{\tau} v \leq 0$, which implies that $(\tau_2, x) \in SR$, if $(\tau_1, x) \in SR$ and $\tau_2 < \tau_1$.



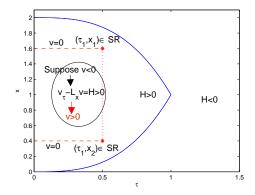
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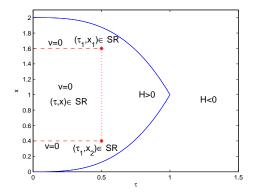
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• With $\mu > 0$, we have $\partial_{\tau} v \leq 0$, which implies that $(\tau_2, x) \in SR$, if $(\tau_1, x) \in SR$ and $\tau_2 < \tau_1$.



- The sell region SR is connected;
- We can define

$$\begin{aligned} x_{1s}^*(\tau) &= \inf\{x \in [0, +\infty) : v(\tau, x) = 0\} \\ x_{2s}^*(\tau) &= \sup\{x \in [0, +\infty) : v(\tau, x) = 0\} \end{aligned}$$

It is easy to show

$$SR = \{(\tau, x) : x_{1s}^*(\tau) \le x \le x_{2s}^*(\tau), 0 < \tau \le \tau^*\}.$$

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• The monotonicity of $x_{is}^*(\tau)$ follows by $\partial_{\tau} v \leq 0$.

Smoothness of the Free Boundary

- For $\mu \ge -\sigma^2$, we have $\partial_{\tau} v \le 0$. So, one can easily establish the smoothness of $x_s^*(\tau)$ following Friedman (1975).
 - First, show $x_s^*(\tau) \in C^{3/4}((0,T])$
 - Then, show $x_s^*(\tau) \in C^1((0,T])$
 - By a bootstrap argument, show $x_s^*(\tau) \in C^\infty((0,T])$

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Smoothness of the Free Boundary

For µ ≥ −σ², we have ∂_τv ≤ 0. So, one can easily establish the smoothness of x^{*}_s(τ) following Friedman (1975).

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- Then, show $x_s^*(\tau) \in C^1((0,T])$
- By a bootstrap argument, show $x_s^*(\tau) \in C^\infty((0,T])$

For μ < −σ², we change of variables. Let y = x − μ/σ²τ, and V(τ, y) = v(τ, x).

- Show $\partial_{\tau}V(\tau,y) \leq 0$ and $\partial_{y}V(\tau,y) \geq 0$
- ▶ Apply Friedman (1975) to show smoothness of the corresponding y^{*}_s(τ), which gives the desired result

Conclusion

- We examine the optimal decision to sell a stock with the criteria of minimizing the square error between the selling price and the global maximum.
- ► For good stock, i.e. µ > 0, the optimal selling boundary has two branches and only exists when time to maturity is not long enough.
- For bad stock, i.e. µ ≤ 0, the optimal selling boundary only has one branch and always exists.

• The smoothness of the free boundary is also established.

Thank you !