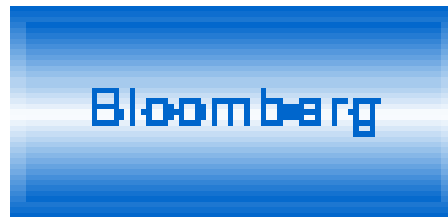


# Functional Itô Calculus and Applications

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# Outline

## 1) **Functional Itô Calculus**

- Functional Itô formula
- Functional Feynman-Kac
- PDE for path dependent options

## 2) **Applications**

- Volatility expansion in LVM
- Vega decomposition
- Robust hedge with Vanillas
- Super-replication and claim decomposition

# 1) Functional Itô Calculus

# Why?

Most often, the impact of uncertainty is cumulative. The link

Cause → Consequence

$$X_t \xrightarrow{f} y_t = f(X_t)$$

depends on certain patterns :

temperature → water level

price history → path dependent payoff

exposure to antigen → viral reaction

interest rate path → MBS prepayment

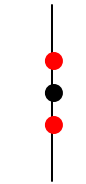
Itô calculus deals with functions of processes.

We extend it to functions of the current path,  
or history, of the process.

# Review of Itô Calculus

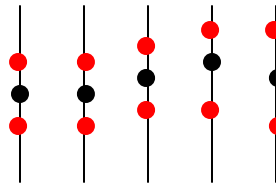
D. <http://ssrn.com/abstract=1435551>

- 1D

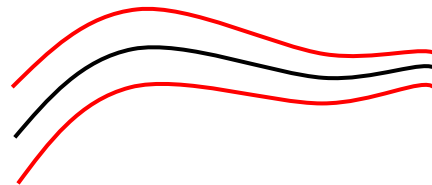


- current value
- possible evolutions

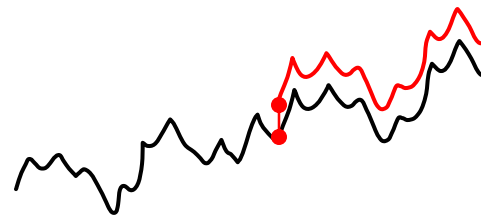
- nD



- infiniteD



- Malliavin Calculus



- Functional Itô Calculus



# Functionals of running paths

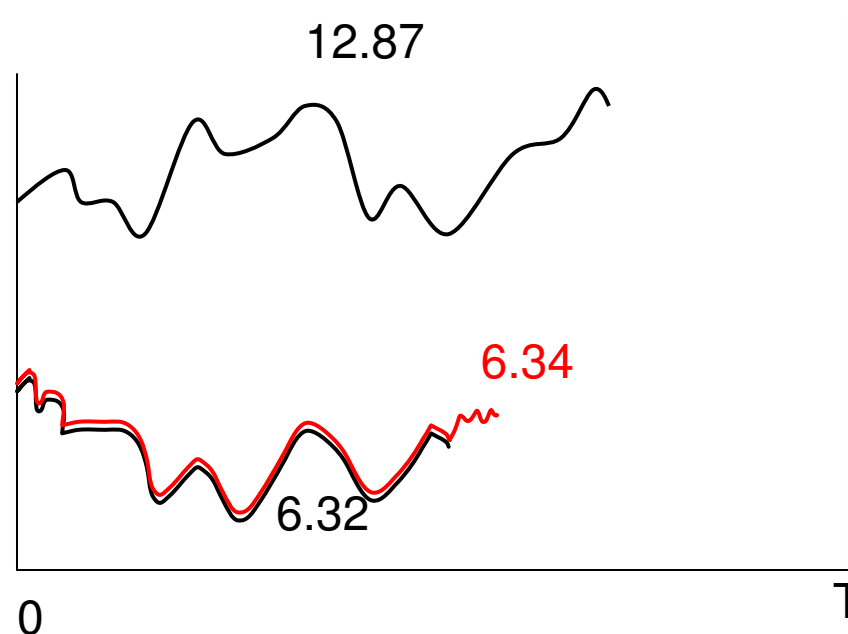
Functionals defined not only on the whole path  $[0, T]$  but on all starting sections  $[0, t]$

$$\Lambda_t \equiv \{\text{RCLL functions } [0, t] \rightarrow \mathfrak{R}\}$$

$$\Lambda \equiv \bigcup_{t \in [0, \bar{T}]} \Lambda_t$$

$f$  functional:  $f : \Lambda \rightarrow \mathfrak{R}$ , for  $X_t \in \Lambda_t$ ,  $f(X_t) \in \mathfrak{R}$

The value of  $X_t$  at  $s \leq t$  is  $X_t(s)$  and  $x_t \equiv X_t(t)$



# Examples of Functionals

- Current average
- Current drawdown
- Conditional expectation of final value
- Super - replicating price

The last one covers the important case of path dependent option price

Finite number of state variables (excluding time) :

- European (1)
- Asian (2)
- Option on range (3)

Infinite number of state variables

- Max of rolling average
- First time last value is hit

# Derivatives

$$\Lambda_t \equiv \{\text{bounded RCLL functions } [0, t] \rightarrow \mathfrak{R}\}, \quad \Lambda \equiv \bigcup_{t \in [0, \bar{T}]} \Lambda_t$$

For  $X_t \in \Lambda_t$ ,  $f : \Lambda \rightarrow \mathfrak{R}$ ,

$$X_t^h(s) \equiv X_t(s) \text{ for } s < t \quad X_t^h(t) = X_t(t) + h$$



$$X_{t, \delta}(s) = X_t(s) \text{ for } s \leq t \quad X_{t, \delta}(s) = X_t(t) \text{ for } s \in [t, t + \delta]$$



Space derivative



$$\Delta_x f(X_t) \equiv \lim_{h \rightarrow 0} \frac{f(X_t^h) - f(X_t)}{h}$$

Time derivative

$$\Delta_t f(X_t) \equiv \lim_{\delta \rightarrow 0} \frac{f(X_{t, \delta}) - f(X_t)}{\delta}$$



# Examples

	$f$	$x_t$	$\int_0^t x_u du$	$QV_t$
	$\Delta_x f$	1	0	$2(x_t - x_{t^-})$
	$\Delta_t f$	0	$x_t$	0

If  $f(X_t) = h(x_t, t)$ , then

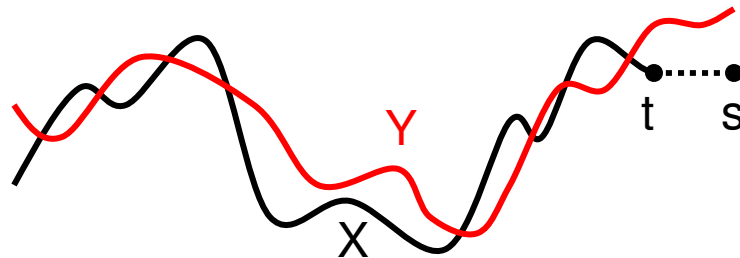
$$\begin{cases} \Delta_x f = \frac{\partial h}{\partial x} \\ \Delta_t f = \frac{\partial h}{\partial t} \end{cases}$$

# Topology and Continuity

$\Lambda$  - distance :

For all  $X_t, Y_s$  in  $\Lambda$ , (we can assume  $t \leq s$ )

$$d_{\Lambda}(X_t, Y_s) \equiv \|X_{t, s-t} - Y_s\|_{\infty} + s - t$$



$\Lambda$  - continuity :

A functional  $f : \Lambda \rightarrow \mathfrak{R}$  is  $\Lambda$  - continuous at  $X_t \in \Lambda$  if :

$$\forall \varepsilon > 0, \exists \alpha > 0 : \forall Y_s \in \Lambda,$$

$$d_{\Lambda}(X_t, Y_s) < \alpha \Rightarrow |f(Y_s) - f(X_t)| < \varepsilon$$

# Functional Itô Formula

Definition : a functional  $f : \Lambda \rightarrow \mathfrak{R}$  is *smooth* if it is  $\Lambda$  - continuous,  $C^2$  in  $x$  and  $C^1$  in  $t$ , with these derivatives themselves  $\Lambda$  - continuous.

## Theorem

If  $x$  is a continuous semi - martingale and  $X_t$  denotes its path over  $[0, t]$ , then, for all smooth functional  $f$  and for all  $T \geq 0$ ,

$$f(X_T) = f(X_0) + \int_0^T \Delta_x f(X_t) dx_t + \int_0^T \Delta_t f(X_t) dt + \frac{1}{2} \int_0^T \Delta_{xx} f(X_t) d\langle x \rangle_t$$

or, in more concise notation,

$$df = \Delta_x f dx + \Delta_t f dt + \frac{1}{2} \Delta_{xx} f d\langle x \rangle$$

# Fragment of proof

$$\begin{aligned}
 df &= f(\overset{\color{red}{\curvearrowright}}{\quad}) - f(\bullet) \\
 &= (f(\overset{\color{red}{\curvearrowright}}{\quad}) - f(\color{red}{\text{---}})) \\
 &+ (f(\color{red}{\text{---}}) - f(\color{red}{\text{---}})) \\
 &+ (f(\color{red}{\text{---}}) - f(\bullet))
 \end{aligned}$$

From Taylor expansion of  $f(Y) - f(Z)$  we get,  
with  $\delta x_i = X_i(\tau) - X_i(\tau_{-i})$  and  $\delta t_i = \tau_i - \tau_{-i}$ ,

$$\begin{aligned}
 B &= \sum_{i=1}^N (f(Y) - f(Z)) = \sum_{i=1}^N \Delta_{i,1} f(Z) \delta x_i & B_1 \\
 &+ \frac{1}{2} \sum_{i=1}^N \Delta_{i,2} f(Z_i^{\theta, \delta t_i}) (\delta x_i)^2 & B_2
 \end{aligned}$$

with  $\theta \in (0,1)$

$$\begin{aligned}
 B_{11} &= \sum_{i=1}^N \Delta_{i,1} f(Z) \delta x_i = \sum_{i=1}^N \Delta_{i,1} f(X_{-i}) \delta x_i & B_{11} \\
 &+ \sum_{i=1}^N (\Delta_{i,1} f(U) - \Delta_{i,1} f(X_{-i})) \delta x_i & B_{12} \\
 &+ \sum_{i=1}^N (\Delta_{i,1} f(Z) - \Delta_{i,1} f(U)) \delta x_i & B_{13}
 \end{aligned}$$

$$B_{11} = \sum_{i=1}^N \Delta_{i,1} f(X_{-i}) \delta x_i \xrightarrow{\delta t_i \rightarrow 0} \int_0^T \Delta_{i,1} f(X) dx$$

$$\text{As } \Delta_{i,1} f(U) - \Delta_{i,1} f(X_{-i}) = \Delta_{i,1} f(X_{-i, \theta \delta t_i}) \delta t_i \leq \beta \max \Delta_{i,1} f, B_{12} \xrightarrow{\delta t_i \rightarrow 0} 0$$

$$\text{As } \Delta_{i,1} f(Z) - \Delta_{i,1} f(U) \leq k, \alpha, B_{13} \xrightarrow{\delta t_i \rightarrow 0} 0$$

$$\begin{aligned}
 2B_2 &= \sum_{i=1}^N \Delta_{i,2} f(Z_i^{\theta, \delta t_i}) (\delta x_i)^2 = \sum_{i=1}^N \Delta_{i,2} f(X_{-i}) (\delta x_i)^2 & B_{21} \\
 &+ \sum_{i=1}^N (\Delta_{i,2} f(Z_i^{\theta, \delta t_i}) - \Delta_{i,2} f(Z)) (\delta x_i)^2 & B_{22} \\
 &+ \sum_{i=1}^N (\Delta_{i,2} f(Z) - \Delta_{i,2} f(X_{-i})) (\delta x_i)^2 & B_{23}
 \end{aligned}$$

$$B_{21} = \sum_{i=1}^N \Delta_{i,2} f(X_{-i}) (\delta x_i)^2 \Rightarrow L_2 - \lim_{\delta t_i \rightarrow 0} B_{21} = \int_0^T \Delta_{i,2} f(X) d\langle x \rangle$$

$$\text{As } |\Delta_{i,2} f(Z_i^{\theta, \delta t_i}) - \Delta_{i,2} f(Z)| \leq k, \alpha, L_2 - \lim_{\delta t_i \rightarrow 0} B_{22} = 0$$

$$\text{As } |\Delta_{i,2} f(Z) - \Delta_{i,2} f(X_{-i})| = |\Delta_{i,2} f(X_{-i, \theta \delta t_i}) \delta t_i| \leq \beta \max \Delta_{i,2} f, L_2 - \lim_{\delta t_i \rightarrow 0} B_{23} = 0$$

$$L_2 - \lim_{\delta t_i \rightarrow 0} B_1 = \int_0^T \Delta_{i,1} f(X) dx$$

$$L_2 - \lim_{\delta t_i \rightarrow 0} B_2 = \frac{1}{2} \int_0^T \Delta_{i,2} f(X) d\langle x \rangle$$

# Functional Feynman-Kac Formula

Generalisation of FK to non Markov dynamics and path dependent payoff.

$$dx_t = a(X_t) dt + b(X_t) dW_t$$

For  $g$  suitably integrable,  $g : \Lambda_T \rightarrow \mathfrak{R}$ ,  $r : \Lambda \rightarrow \mathfrak{R}$ . We define  $f : \Lambda \rightarrow \mathfrak{R}$  by

$$f(Y_t) \equiv E[e^{-\int_t^T r(Z_u) du} g(Z_T) | Z_t = Y_t]$$

where  $\begin{cases} \text{for } u \in [0, t], Z_T(u) = Y_t(u) \\ \text{for } u \in [t, T], dz_u = a(Z_u) du + b(Z_u) dW_u \end{cases}$

Then, if  $f$  is smooth, it satisfies

$$\Delta_t f(X_t) + a(X_t) \Delta_x f(X_t) - r(X_t) f(X_t) + \frac{b^2(X_t)}{2} \Delta_{xx} f(X_t) = 0$$

(apply functional Itô formula to the martingale  $e^{-\int_0^t r(X_u) du} f(X_t)$ )

# Delta Hedge/Clark-Ocone

If  $f$  defined by  $f(Y_t) \equiv E[g(Z_T) | Z_t = Y_t]$  is smooth, then we have the explicit Martingale Representation :

$$g(X_T) = E[g(X_T) | X_0] + \int_0^T b(X_t) \Delta_x f(X_t) dW_t$$

From functional Itô and Feynman - Kac with  $r = 0$ ,

$$df(X_t) = b(X_t) \Delta_x f(X_t) dW_t$$

and

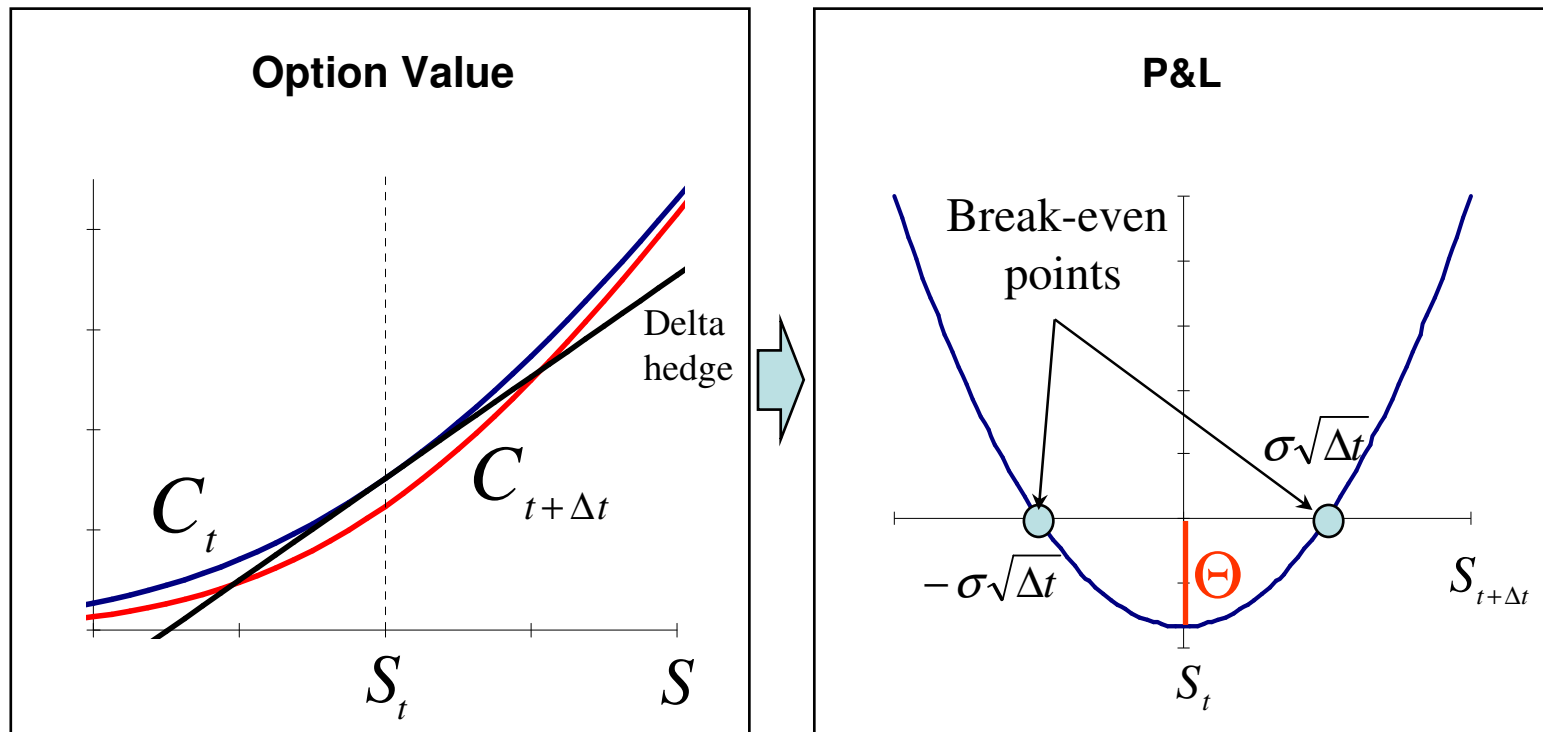
$$g(X_T) = f(X_T) = f(X_0) + \int_0^T b(X_t) \Delta_x f(X_t) dW_t$$

It can be compared to the Clark - Ocone formula

from Malliavin Calculus :

$$g(X_T) = E[g(X_T) | X_0] + \int_0^T b(X_t) E[D_t g(X_T) | X_t] dW_t$$

# P&L of a delta hedged Vanilla



# Functional PDE for Exotics

If  $f$  given by  $f(Y_t) \equiv E[e^{-\int_t^T r(Z_u) du} g(Z_T) | Z_t = Y_t]$  is smooth, then it satisfies

$$\Delta_t f(X_t) + \frac{1}{2} b^2 \Delta_{xx} f(X_t) + r(X_t) (\Delta_x f(X_t) x_t - f(X_t)) = 0$$


The  $\Gamma/\Theta$  trade - off for European options also holds for path dependent options, even with an infinite number of state variables. However, in general  $\Gamma$  and  $\Theta$  will be path dependent.




# Classical PDE for Asian

Payoff of Asian Call:  $g(X_T) = (\int_0^T x_u du - K)^+$

Assume  $dx_t = b(x_t, t) dW_t$  Define  $I_t \equiv \int_0^t x_u du$ ,  $f(X_t) \equiv l(x_t, I_t, t)$



$$\Delta_t I = x_t \Rightarrow \Delta_t f = x \frac{\partial l}{\partial I} + \frac{\partial l}{\partial t}$$



$$\Delta_x I = 0 \Rightarrow \Delta_x f = \frac{\partial l}{\partial x}, \Delta_{xx} f = \frac{\partial^2 l}{\partial x^2}$$

$$\Delta_t f + \frac{1}{2} b^2 \Delta_{xx} f = 0 \Rightarrow \frac{\partial l}{\partial t} + x \frac{\partial l}{\partial I} + \frac{1}{2} b^2 \frac{\partial^2 l}{\partial x^2} = 0$$

$x \frac{\partial l}{\partial I}$  is a bothering convection term.

# Better Asian PDE

Define  $J_t \equiv E_t[\int_0^T x_u du] = \int_0^t x_u du + (T-t)x_t$ ,  $f(X_t) \equiv h(x_t, J_t, t)$



$$\Delta_t J = 0 \Rightarrow \Delta_t f = \frac{\partial h}{\partial t}$$



$$\Delta_x J = (T-t) \Rightarrow \begin{cases} \Delta_x f = \frac{\partial h}{\partial x} + (T-t) \frac{\partial h}{\partial J} \\ \Delta_{xx} f = \frac{\partial^2 h}{\partial x^2} + 2(T-t) \frac{\partial^2 h}{\partial x \partial J} + (T-t)^2 \frac{\partial^2 h}{\partial J^2} \end{cases}$$

$$\Delta_t f + \frac{1}{2} b^2 \Delta_{xx} f = 0 \Rightarrow \frac{\partial h}{\partial t} + \frac{1}{2} b^2 \left( \frac{\partial^2 h}{\partial x^2} + 2(T-t) \frac{\partial^2 h}{\partial x \partial J} + (T-t)^2 \frac{\partial^2 h}{\partial J^2} \right) = 0$$

## 2) Robust Volatility Hedge

# Local Volatility Model

- Simplest model to fit a full surface
- Forward volatilities that can be locked

$$\frac{dS}{S} = (r - q) dt + \sigma(S, t) dW$$

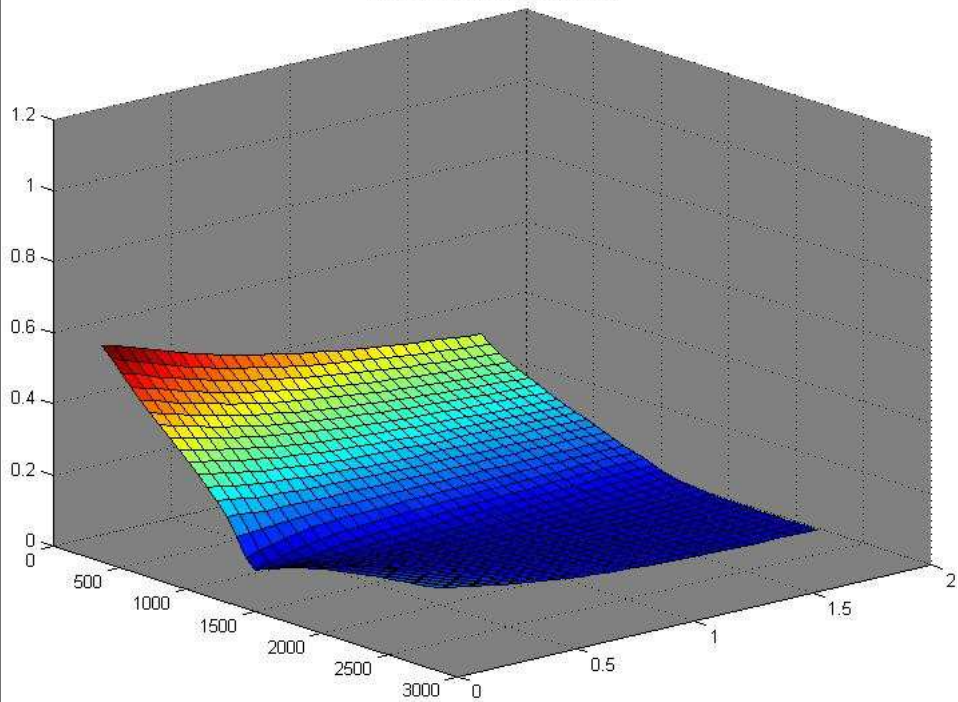
$$\frac{\partial C}{\partial T} = \frac{\sigma^2(K, T)}{2} K^2 \frac{\partial^2 C}{\partial K^2} - (r - q) K \frac{\partial C}{\partial K} - q \cdot C$$

# Summary of LVM

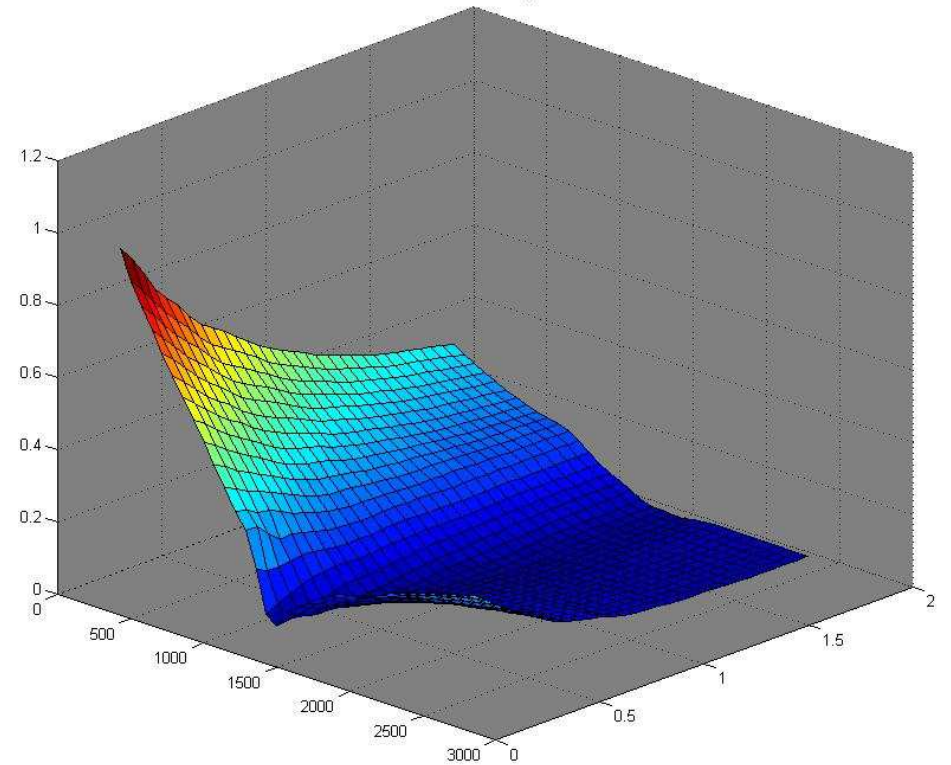
- Simplest model that fits vanillas
- In Europe, second most used model (after Black-Scholes) in Equity Derivatives
- Local volatilities: fwd vols that can be locked by a vanilla PF
- Stoch vol model calibrated  $E[\sigma_t^2 | S_t = S] = \sigma_{loc}^2(S, t)$
- If no jumps, deterministic implied vols => LVM

# S&P500 implied and local vols

S&P500 implied volatility surface



S&P 500 local volatility surface



# Hedge within/outside LVM

- 1 Brownian driver => complete model
- Within the model, perfect replication by Delta hedge
- Hedge outside of (or against) the model: hedge against volatility perturbations
- Leads to a decomposition of Vega across strikes and maturities

# P&L from Delta hedging

Assume  $r = q = 0$ ,  $dx_t = \sqrt{v_0(x_t, t)} dW_t$ .

For  $g \in \Lambda_T$ , define  $f \in \Lambda$  by  $f(X_t) \equiv E^{\mathcal{Q}_{v_0}}[g(X_T)|X_t]$

By functional PDE,  $\Delta_t f(X_t) + \frac{1}{2} v_0(x_t, t) \Delta_{xx} f(X_t) = 0$

If  $y$  follows  $dy_t = \sqrt{v_t} dW_t$  with  $y_0 = x_0$ , by the functional Itô formula,

$$\begin{aligned} g(Y_T) = f(Y_T) &= f(Y_0) + \int_0^T \Delta_x f(Y_t) dy_t + \int_0^T \Delta_t f(Y_t) dt + \frac{1}{2} \int_0^T v_t \Delta_{xx} f(Y_t) dt \\ &= f(X_0) + \int_0^T \Delta_x f(Y_t) dy_t + \frac{1}{2} \int_0^T (v_t - v_0(y_t, t)) \Delta_{xx} f(Y_t) dt \end{aligned}$$



# Model Impact

Recall

$$g(Y_T) = f(Y_T) = f(X_0) + \int_0^T \Delta_x f(Y_t) dy_t + \frac{1}{2} \int_0^T (v_t - v_0(y_t, t)) \Delta_{xx} f(Y_t) dt$$

Hence, with  $\Pi_g(v) \equiv E^{Q_v} [g(Y_T) | X_0]$  and  $\phi^v(x, t)$  the transition density for  $v$ ,

$$\begin{aligned} \Pi_g(v) &= \Pi_g(v_0) + \frac{1}{2} E^{Q_v} \left[ \int_0^T (v_t - v_0(x_t, t)) \Delta_{xx} f(X_t) dt \right] \\ &= \Pi_g(v_0) + \frac{1}{2} \int_0^T \int \phi^v(x, t) E^{Q_v} [(v_t - v_0(x, t)) \Delta_{xx} f(X_t) | x_t = x] dx dt \end{aligned}$$

# Comparing calibrated models

Recall

$$\Pi_g(v) = \Pi_g(v_0) + \frac{1}{2} \int_0^T \int \phi^v(x,t) E^{\mathcal{Q}_v} [(v_t - v_0(x,t)) \Delta_{xx} f(X_t) | x_t = x] dx dt$$

For a knock-out Barrier option,

$$\begin{aligned} \Pi_g(v) - \Pi_g(v_0) &= \frac{1}{2} \int_0^T \int \phi^v(x,t) E^{\mathcal{Q}_v} [(v_t - v_0(x,t)) \Delta_{xx} f(X_t) | x_t = x] dx dt \\ &= \frac{1}{2} \int_0^T \int \phi^v(x,t) P_{alive}(x,t) E^{\mathcal{Q}_v} [(v_t - v_0(x,t)) \Delta_{xx} f(X_t) | x_t = x, alive] dx dt \\ &= \frac{1}{2} \int_0^T \int \phi_{alive}^v(x,t) \frac{\partial^2 f_{alive}(x,t)}{\partial x^2} E^{\mathcal{Q}_v} [(v_t - v_0(x,t)) | x_t = x, alive] dx dt \end{aligned}$$

If  $v$  and  $v_0$  are calibrated on the same vanilla options,  $E^{\mathcal{Q}_v} [v_t | x_t = x] = v_0(x,t)$

It amounts to evaluate the impact of conditioning by "alive":

$$E^{\mathcal{Q}_v} [v_t | x_t = x, alive] - E^{\mathcal{Q}_v} [v_t | x_t = x]$$

# Volatility Expansion in LVM

In general,

$$\Pi_g(v) = \Pi_g(v_0) + \frac{1}{2} \int_0^T \int \phi^v(x, t) E^{Q_v} [(v_t - v_0(x, t)) \Delta_{xx} f(X_t) | x_t = x] dx dt$$

In the case where  $v$  is a LVM of the form  $v_0 + u : dx_t = \sqrt{v_0(x_t, t) + u(x_t, t)} dW_t$

$$\begin{aligned} \Pi_g(v_0 + u) &= \Pi_g(v_0) + \frac{1}{2} \int_0^T \int \phi^{v_0+u}(x, t) u(x, t) E^{Q_{v_0+u}} [\Delta_{xx} f(X_t) | x_t = x] dx dt \\ &= \Pi_g(v_0) + \int_0^T \int m(x, t) u(x, t) dx dt \end{aligned}$$

where  $m(x, t) \equiv \frac{1}{2} \phi^{v_0+u}(x, t) E^{Q_{v_0+u}} [\Delta_{xx} f(X_t) | x_t = x]$

# Fréchet Derivative in LVM

In particular,

$$\Pi_g(v_0 + \varepsilon u) = \Pi_g(v_0) + \frac{\varepsilon}{2} \int_0^T \int \phi^{v_0 + \varepsilon u}(x, t) u(x, t) E^{Q_{v_0 + \varepsilon u}} [\Delta_{xx} f(X_t) | x_t = x] dx dt$$

The Fréchet derivative in the direction of  $u$  satisfies :

$$\begin{aligned} \langle \nabla_v \Pi_g, u \rangle &\equiv \lim_{\varepsilon \rightarrow 0} \frac{\Pi_g(v_0 + \varepsilon u) - \Pi_g(v_0)}{\varepsilon} \\ &= \frac{1}{2} \int_0^T \int \phi^{v_0}(x, t) u(x, t) E^{Q_{v_0}} [\Delta_{xx} f(X_t) | x_t = x] dx dt \\ &= \int_0^T \int m(x, t) u(x, t) dx dt \end{aligned}$$

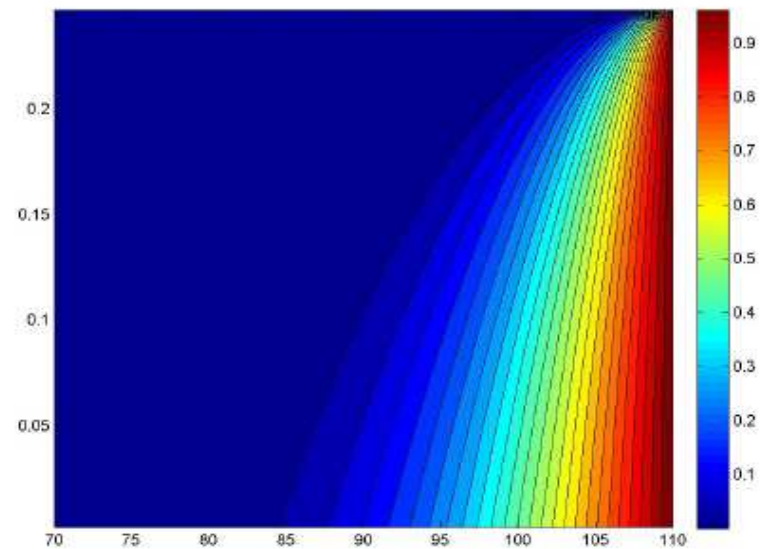
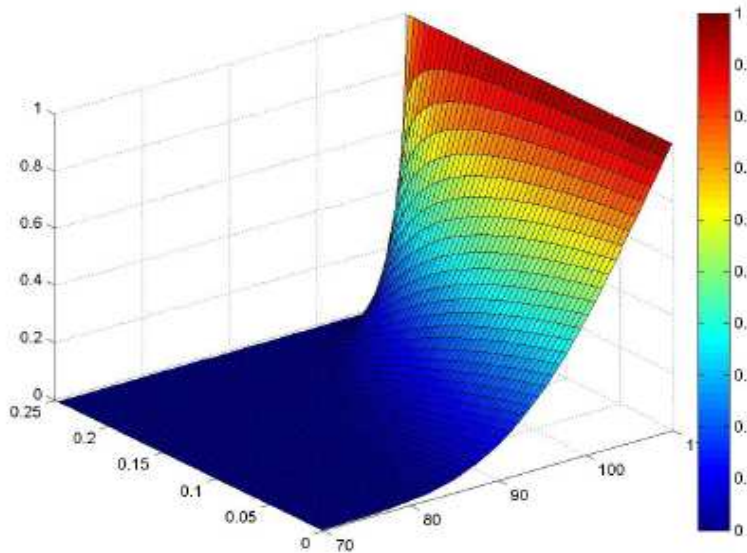
where

$$m(x, t) \equiv \frac{1}{2} \phi^{v_0}(x, t) E^{Q_{v_0}} [\Delta_{xx} f(X_t) | x_t = x]$$

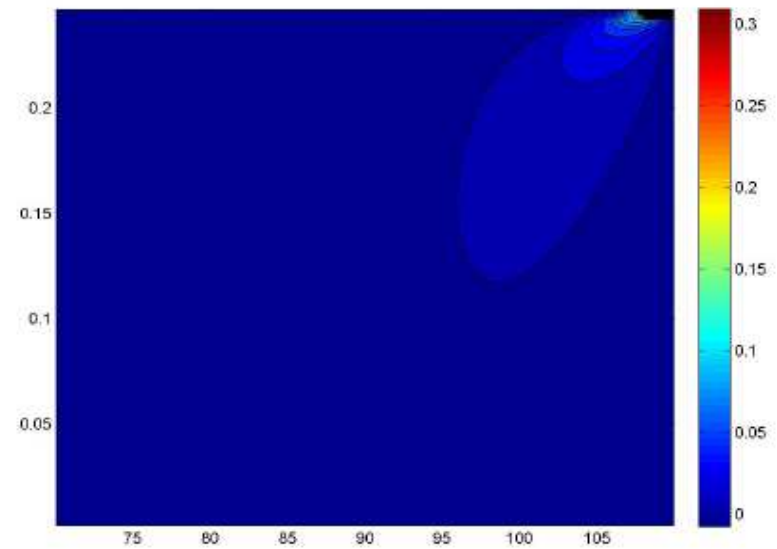
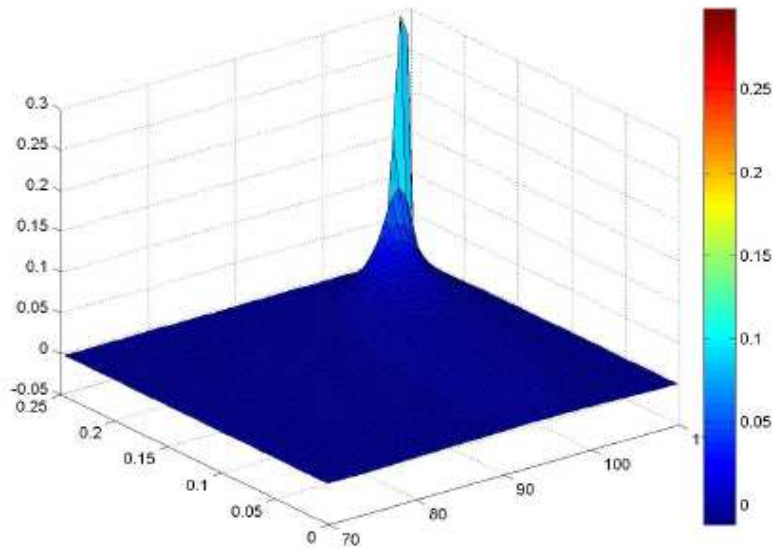
is the sensitivity of  $g$  to the local variance at  $(x, t)$  (Fréchet derivative)

# One Touch Option - Price

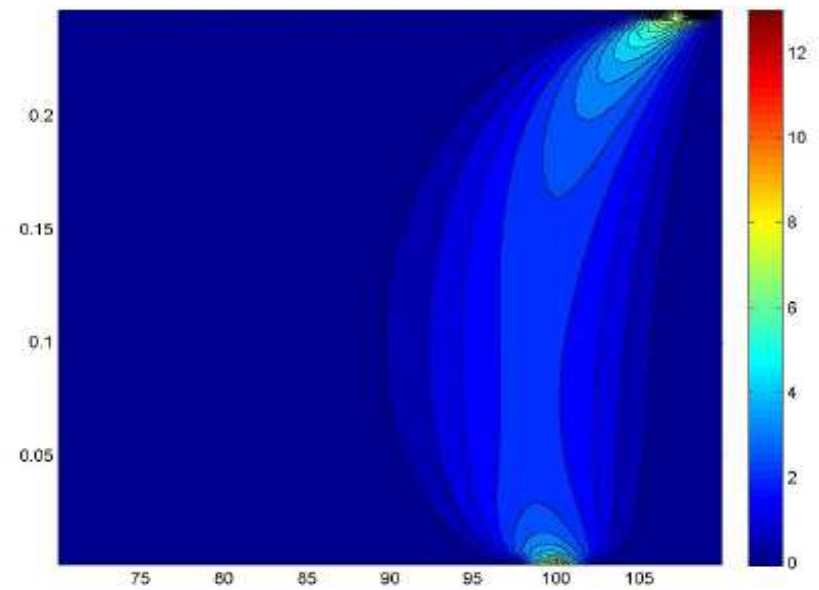
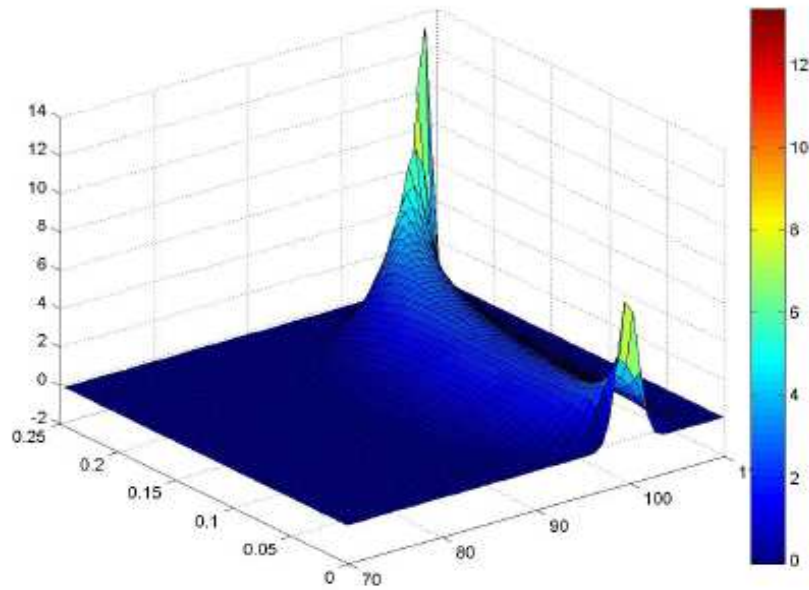
Black-Scholes model  $S_0=100$ ,  $H=110$ ,  $\sigma=0.25$ ,  $T=0.25$



# One Touch Option - $\Gamma$

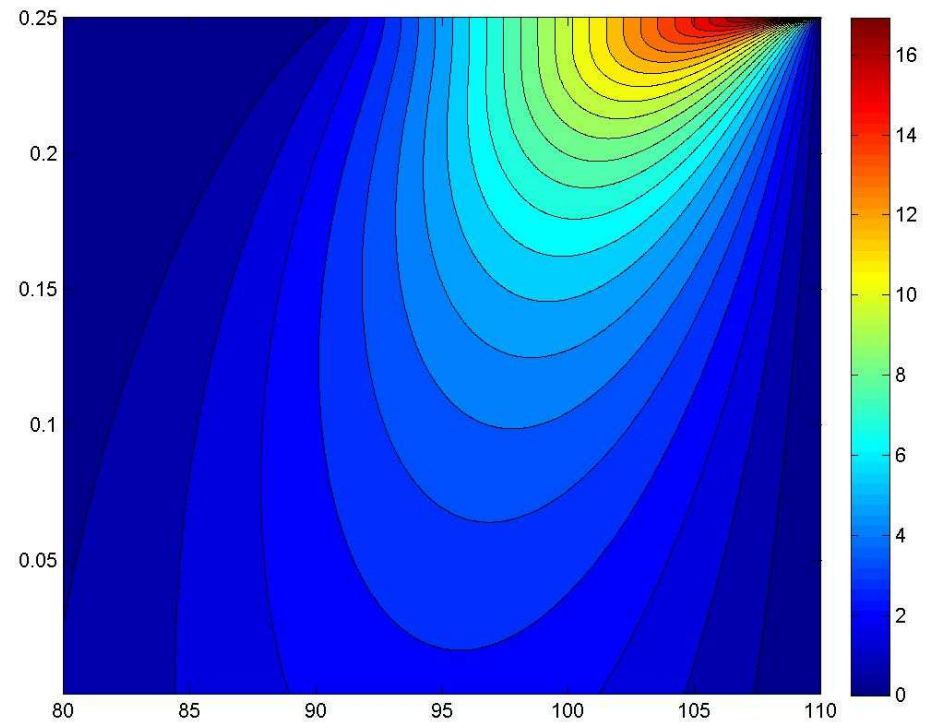
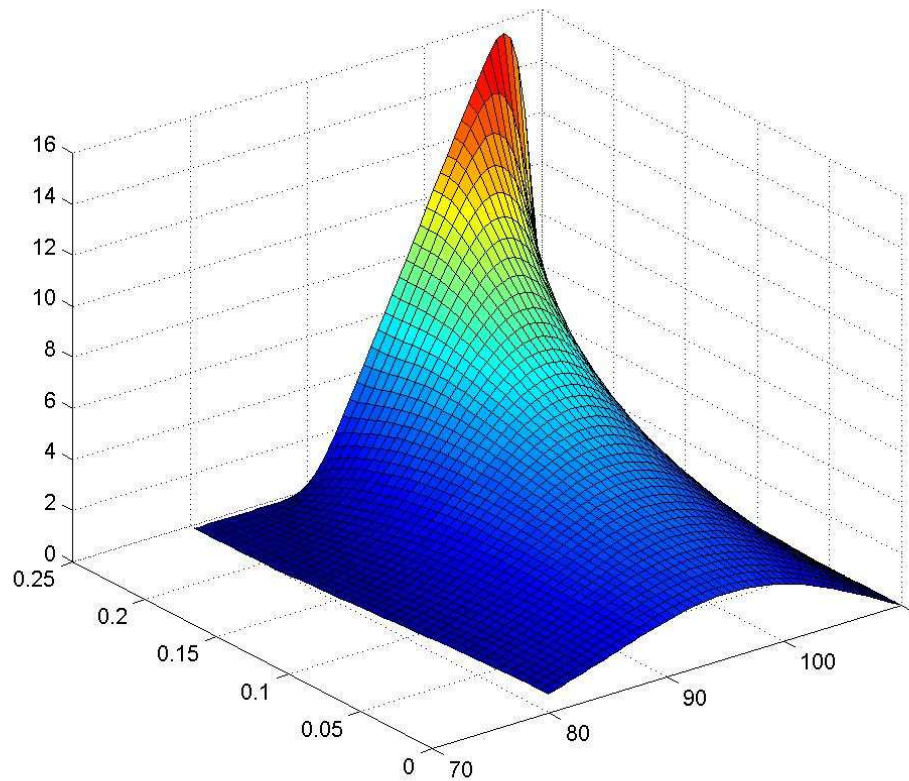


$$O.T.: m(S, t) = \frac{1}{2} \Gamma \cdot \phi \cdot P$$



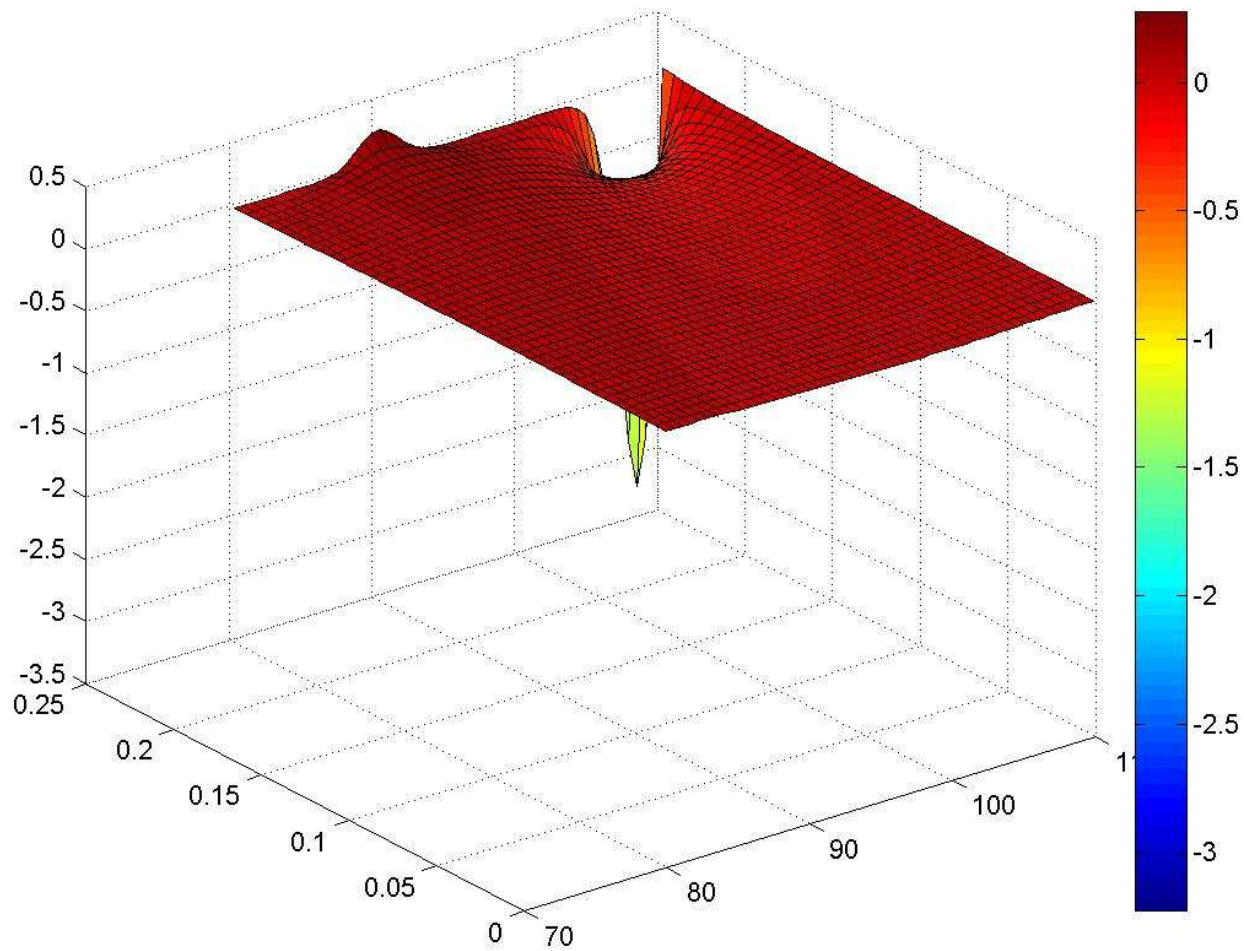
# Up-Out Call - Price

Black-Scholes model  $S_0=100$ ,  $H=110$ ,  $K=90$ ,  $\sigma=0.25$ ,  $T=0.25$

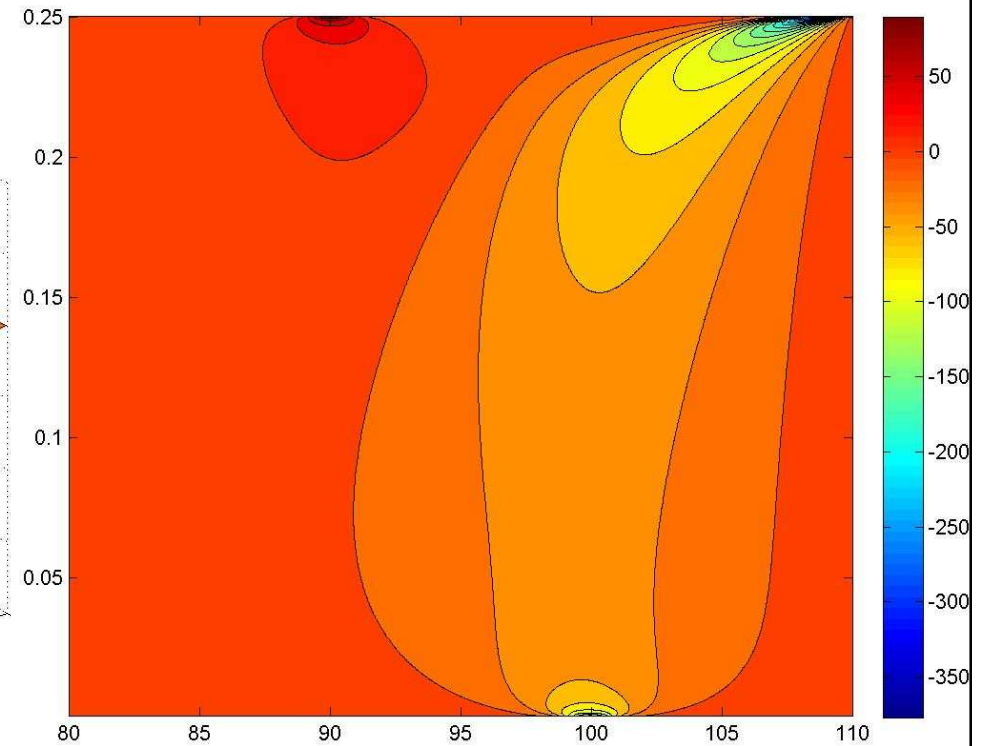
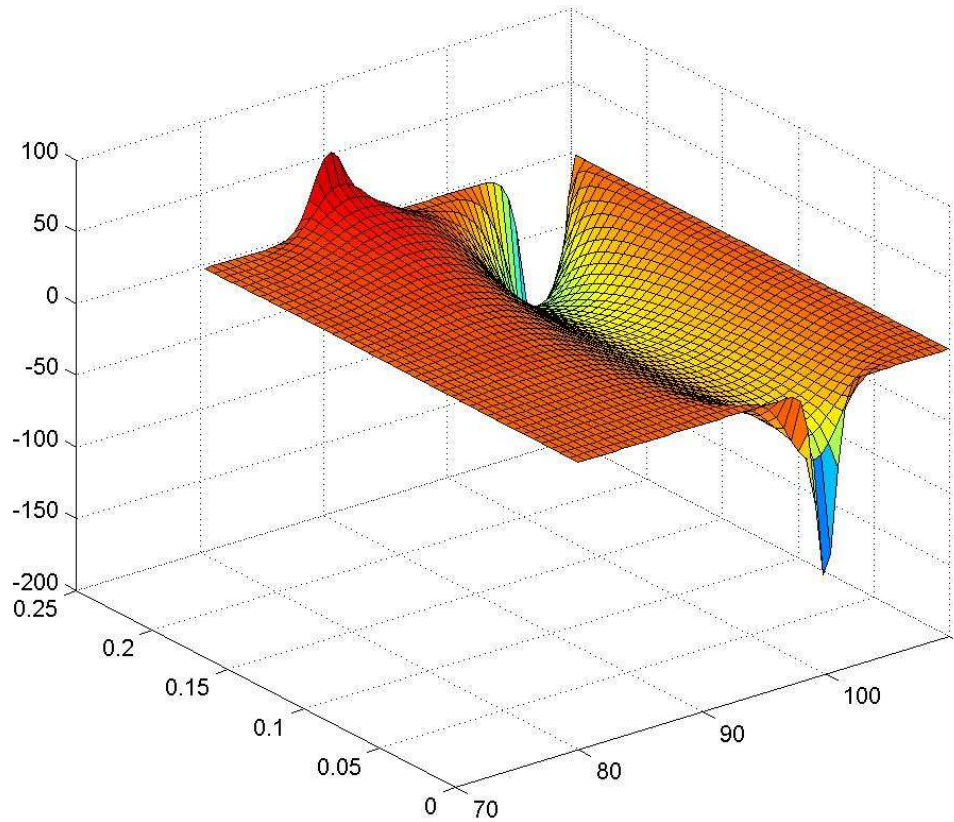




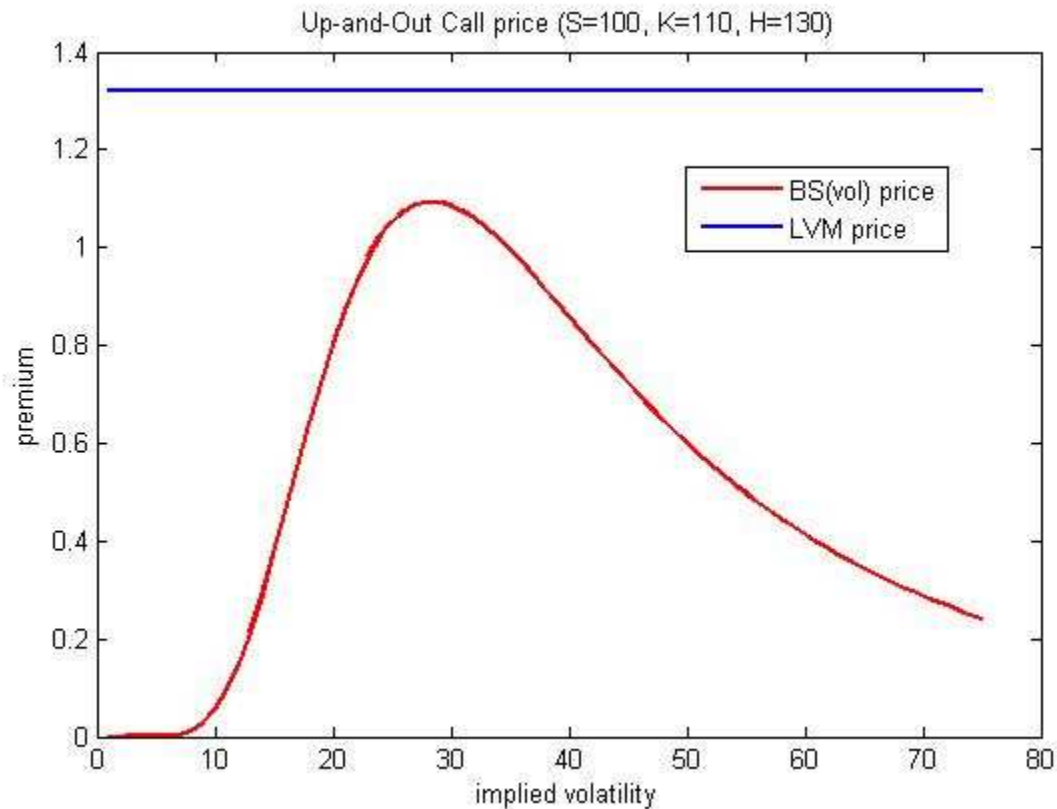
# Up-Out Call - $\Gamma$



$$UOC : m(S, t) = \frac{1}{2} \Gamma \cdot \varphi \cdot P$$



# Black-Scholes/LVM comparison



In this case, no volatility input of the Black - Scholes enables to reach the LVM price.

# Vanilla hedging portfolio I

Recall  $m(x, t) \equiv \frac{1}{2} \phi^{v_0}(x, t) E^{\mathcal{Q}_{v_0}} [\Delta_{xx} f(X_t) | x_t = x]$  is the sensitivity of  $\Pi_g$  to the local variance at  $(x, t)$ .

Portfolio  $PF = \iint \alpha(K, T) C_{K, T} dK dT$  of vanillas hedges all small volatility moves if and only if for all  $(x, t)$

$$\frac{\partial^2 PF(x, t)}{\partial x^2} = E^{\mathcal{Q}_{v_0}} [\Delta_{xx} \Pi_{PF}(X_t) | x_t = x] = E^{\mathcal{Q}_{v_0}} [\Delta_{xx} f(X_t) | x_t = x] \equiv h(x, t)$$

How can we get the function  $\alpha(K, T)$ ?

# Vanilla hedging portfolios II

a) For  $k(x, t)$ , we define  $L(k) \equiv \frac{\partial k}{\partial t} + \frac{1}{2} \frac{\partial^2 (v_0 k)}{\partial x^2}$

For a call  $C_{K,T}$ ,  $L\left(\frac{\partial^2 C_{K,T}}{\partial x^2}\right) = 0$  with boundary condition  $\frac{\partial^2 C_{K,T}}{\partial x^2}(x, T) = \delta_K(x)$

b)  $PF \equiv \iint \alpha(K, T) C_{K,T} dK dT \Rightarrow L\left(\frac{\partial^2 PF}{\partial x^2}\right)(x, t) = -\alpha(x, t)$

$k(x, t) \equiv E^{Q_0}[\Delta_{xx} f(X_t) - \frac{\partial^2 PF}{\partial x^2}(x, t) | x_t = x] = h(x, t) - \frac{\partial^2 PF}{\partial x^2}(x, t)$  with  $h(x, t) \equiv E^{Q_0}[\Delta_{xx} f(X_t) | x_t = x]$

Thus,  $L(k) = L(h) + \alpha$ .

c) If we take  $\alpha = -L(h) = -\frac{\partial h}{\partial t} - \frac{1}{2} \frac{\partial^2 (v_0 h)}{\partial x^2}$  then  $L(k) = 0$  with  $k(x, T) = 0 \Rightarrow k \equiv 0$

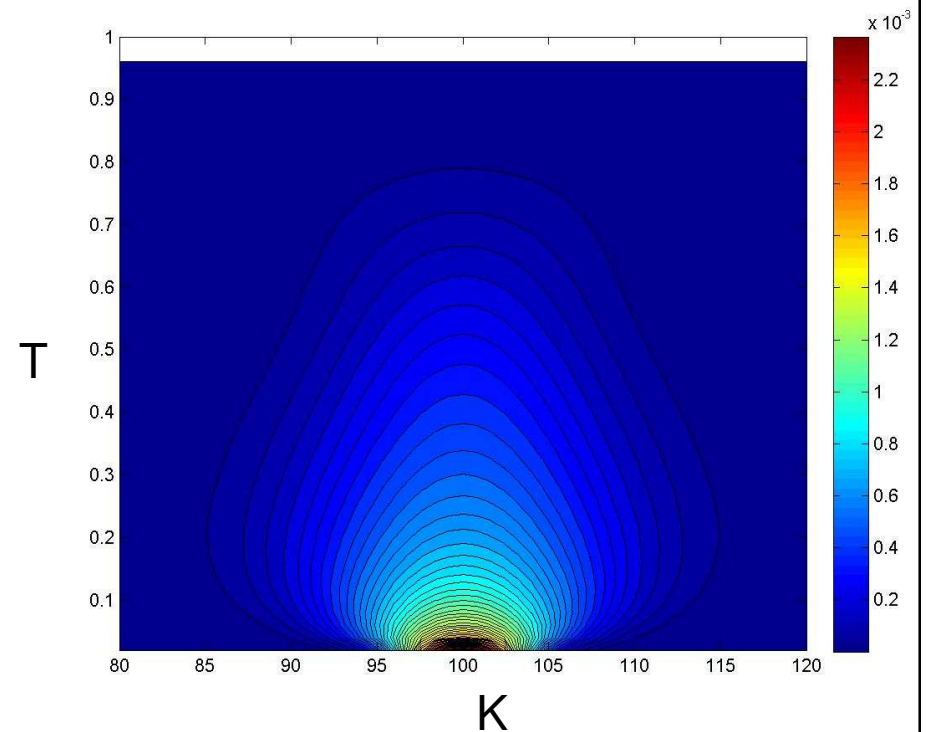
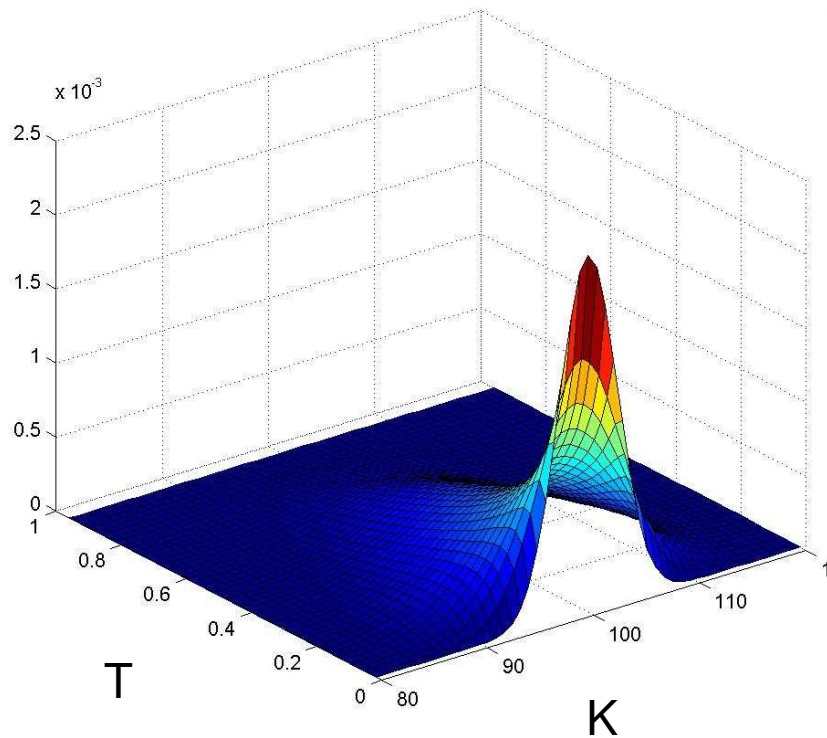
$\forall x, t, E^{Q_0}[\Delta_{xx} f(X_t) - \frac{\partial^2 PF}{\partial x^2}(x, t) | x_t = x] = 0$  and  $f - PF$  has no sensitivity to local vol bumps

hence no sensitivity to implied vol bumps.

# Example : Asian option

$$dx_t = \sqrt{v_0} dW_t \quad \text{Pay-off : } g(X_t) = \left( \int_0^T x_t dt - K \right)^+, S_0 = K = 100 \quad \text{volatility } \sqrt{v_0} = 20 \quad \text{maturity } T = 1$$

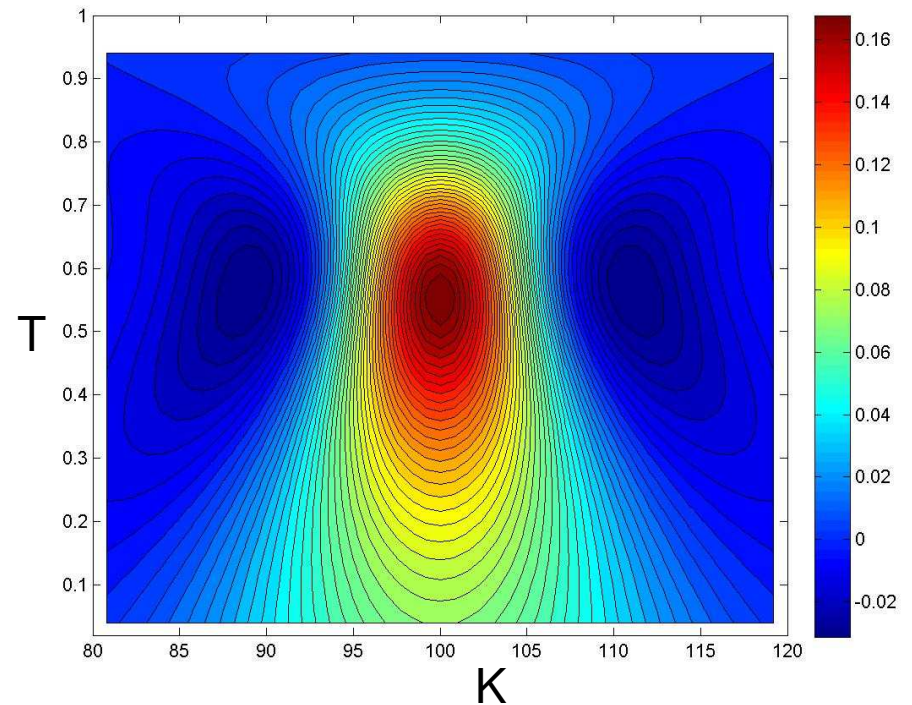
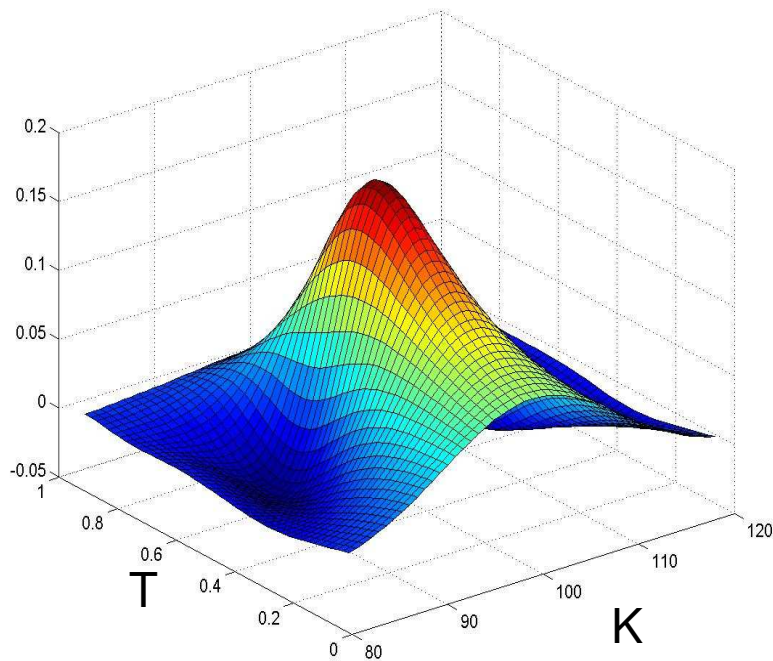
$$m(x, t) \equiv \frac{1}{2} \phi^{v_0}(x, t) E^{Q_{v_0}} [\Delta_{xx} f(X_t) | x_t = x] \text{ is the sensitivity of } \Pi_g \text{ to the local variance at } (x, t).$$



# Asian Option Hedge

Robust volatility hedge with  $PF \equiv \iint \alpha(K, T) C_{K, T} dK dT$

$$\alpha(K, T) = - \left( \frac{\partial h(K, T)}{\partial t} + \frac{1}{2} \frac{\partial^2 (v_0(K, T) h(K, T))}{\partial x^2} \right)$$

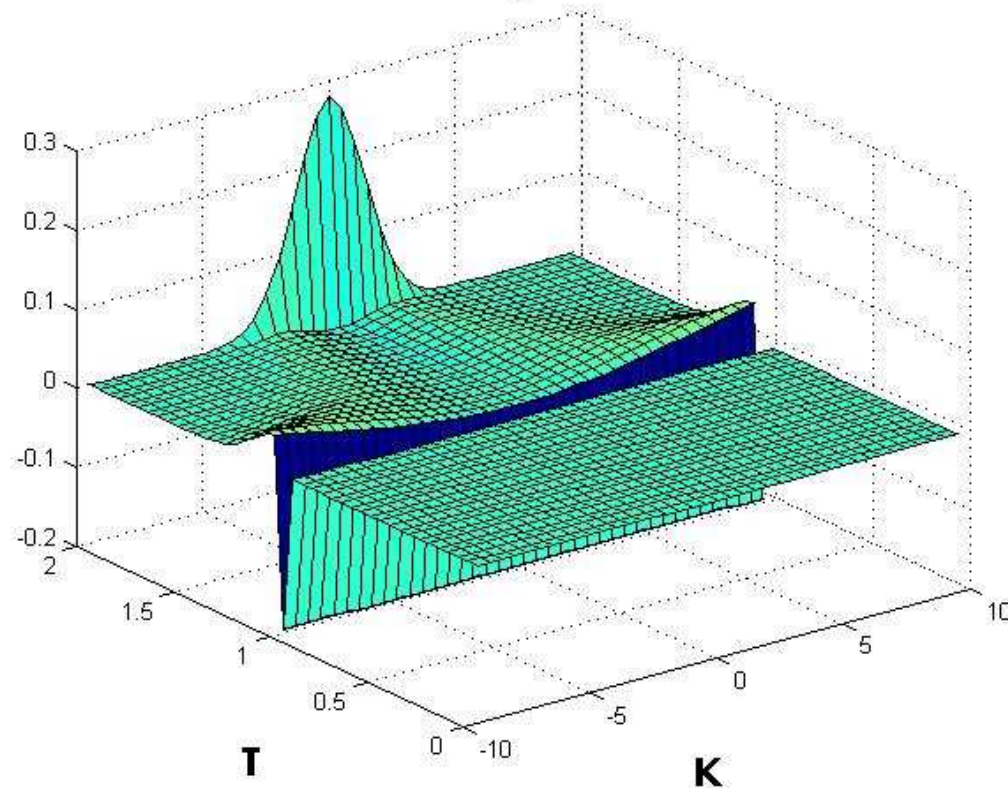


# Fwd Start Option Hedge

$$g(X_{T_2}) = (x_{T_2} - x_{T_1})^+$$

Robust volatility hedge with  $PF \equiv \iint \alpha(K, T) C_{K, T} dK dT$

**Forward Start Option Coefficients**





# Link $\Gamma/Vega$

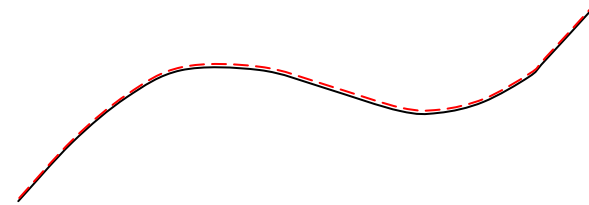
Cancel		Insensitive to
$\Gamma$	$\Gamma = 0$	temporary shocks in $\sigma$
<i>Vega</i>	$\mathbb{E} \left[ \int_0^T S_t^2 \Gamma_t dt \right] = 0$	persistent shocks in $\sigma$
Superbucket	$\forall S, t \mathbb{E} [\Gamma_t   S_t = S] = 0$	<ul style="list-style-type: none"> <li>• any temporary shocks in <math>\sigma</math> in the future</li> <li>• any small shocks in implied volatility today</li> </ul>

# **SUPER-REPLICATION/ CLAIM DECOMPOSITION**

# Claim Pricing

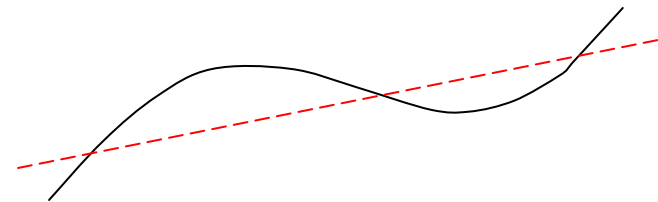
- Complete Markets

- perfect replication
- unique price



- Incomplete Markets

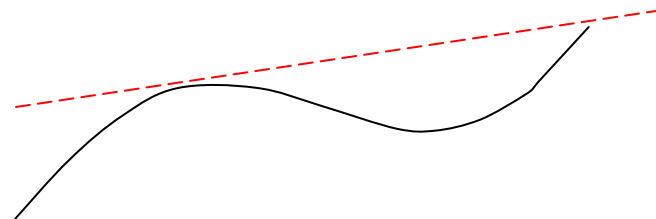
- imperfect replication
- range of prices



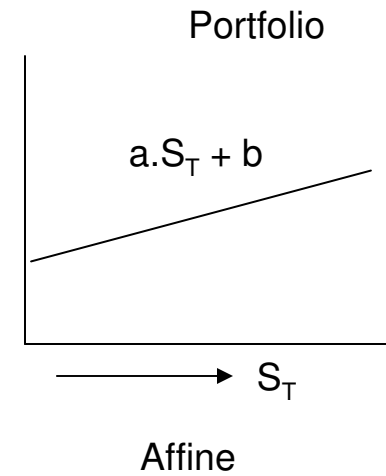
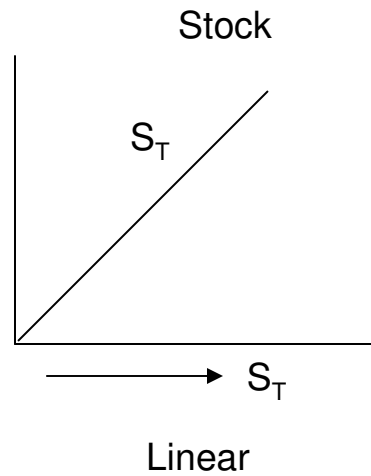
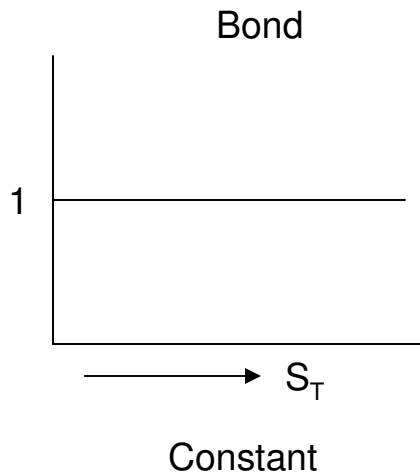
- Minimum variance hedge

- Indifference pricing (utility based)

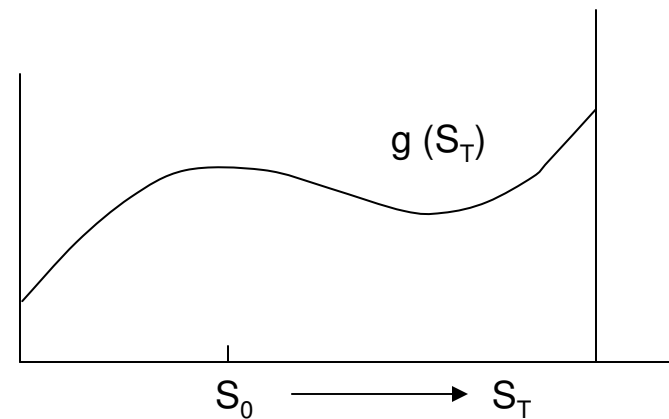
- Super-replication



# Static hedge in Stocks and Bonds



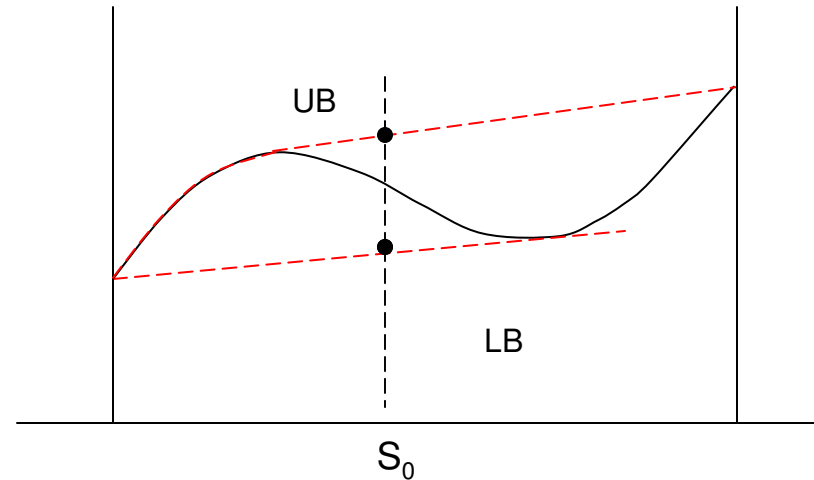
Claim gives  $g(S_T)$  at T



Arbitrage free prices for the claim at 0 ?

# Arbitrage free prices for $g$

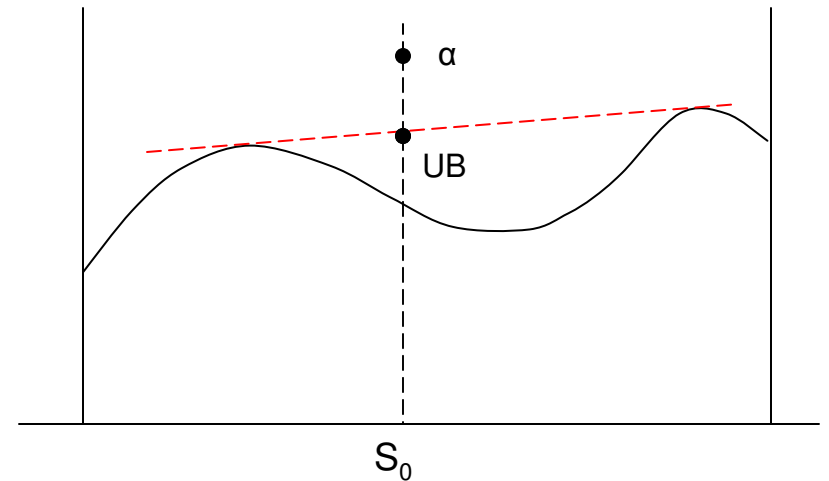
1. Take convex hull of  $(S, g(S))$  in the plane
2. Intersect with the vertical line at  $S_0$



# Price Range

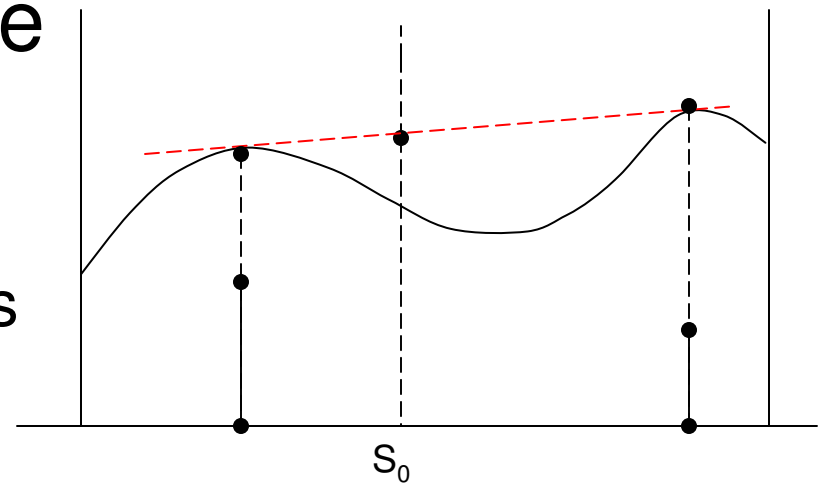
## 1. If $\alpha > UB$

- Sell Claim for  $\alpha$
- Buy super-replication for UB



## 2. Prices in (LB, UB) are possible

- Binomial model with states = contact points



# Theory of static case

- Delbaen-Schachermayer (1994): Duality Result

- Price decomposition

– With static position in options and dynamic position in stocks

where  $C_i^0$  is the price of option  $C_i$  at  $0$

# Continuous time case

- El Karoui - Quenez (1995): LB is a submartingale
- Dynamic version of Delbaen - Schachermayer (1994)
- Kramkov (1996): Optimal decomposition theorem

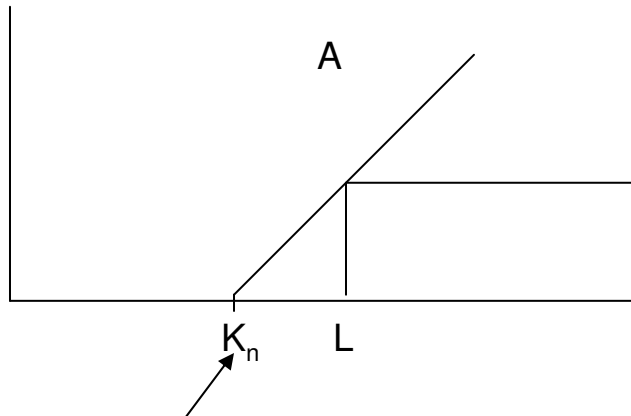
where  $k$  is a non decreasing process

- Interpretation: The increasing process  $k$  comes from improving LB whenever you can
- In other words, if you prepare for the worst, you can only have good surprises

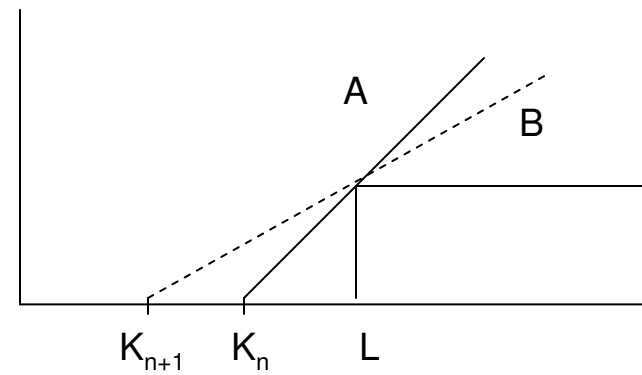


# One Touch example

- A super-replication A put in place today will still work tomorrow. If a cheaper one, B is available tomorrow, roll from A to B to collect the improvement



Optimal strike at  $t_n$ : minimize  $\frac{1}{L-K} C_K \geq OT_L$



Optimal strike at  $t_{n+1}$

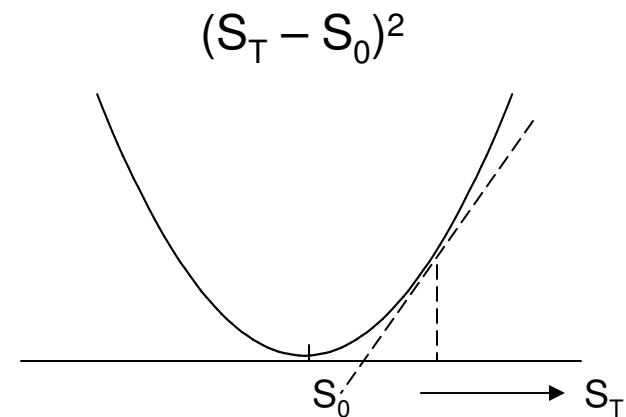
- If at  $t_{n+1}$   $B = \frac{1}{L-K_{n+1}} C_{K_{n+1}}$  is cheaper than  $A = \frac{1}{L-K_n} C_{K_n}$
- Sell  $A(t_n)$  and buy  $B(t_{n+1})$ : you collect the difference and still super-replicate

# Parabola Example

- If you delta hedge at stopping times  $\tau_i$ , you collect the discrete quadratic variation

$$\sum (S_{\tau_i} - S_{\tau_{i-1}})^2$$

(mechanics of Variance Swaps)



- No hedge  $(S_T - S_0)^2$
- Hedge at  $\tau_i$   $\sum (S_{\tau_i} - S_{\tau_{i-1}})^2$
- Continuous hedge  $\langle S \rangle_T$  (quadratic variation of  $S$ )

# European Case 1 period

$$g = LB + a + k$$

$g$  : claim

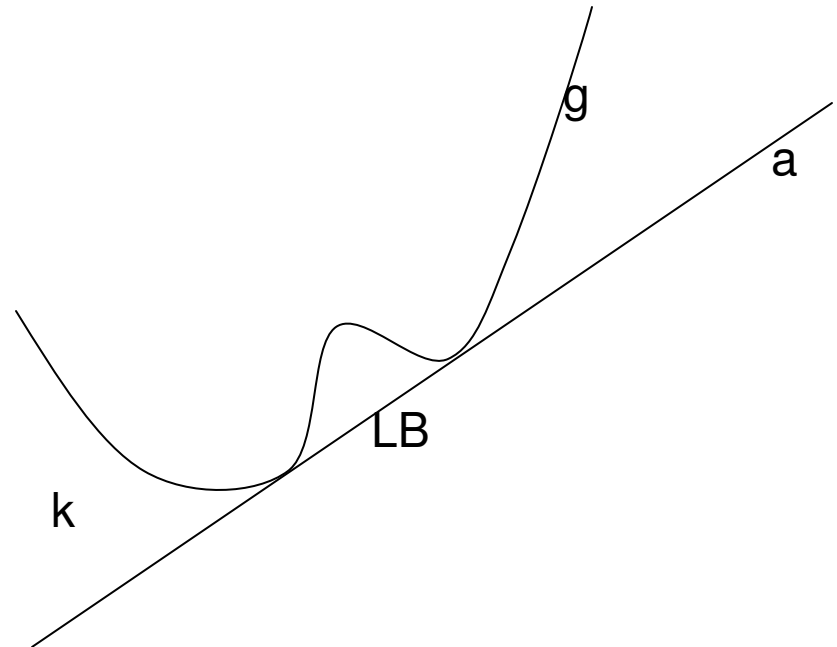
$LB$  : lower bound

$a$  : costless attainable claim

$k$  : non negative claim

$LB + a$  is the sub - hedge, a static position in ZC and asset

$k$  is a possible payment to be collected at maturity

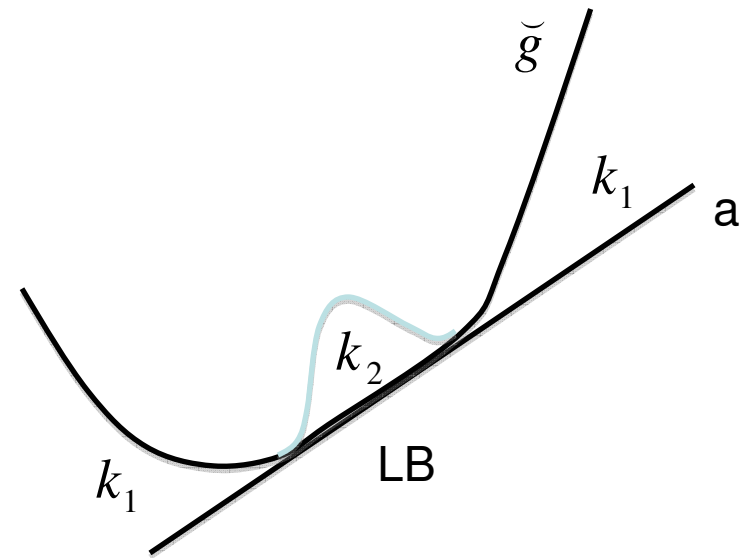


# European Case Continuous Time

$$g = LB + a + k_1 + k_2$$

$k_1, k_2$  : non negative claims

$LB + a + k_1$  : convex hull of  $X$



$k_1$  : convex claim that can be hedged in many ways

$k_2$  is a possible payment to be collected at maturity

$$\text{ConvexHull}(k_2) = 0$$

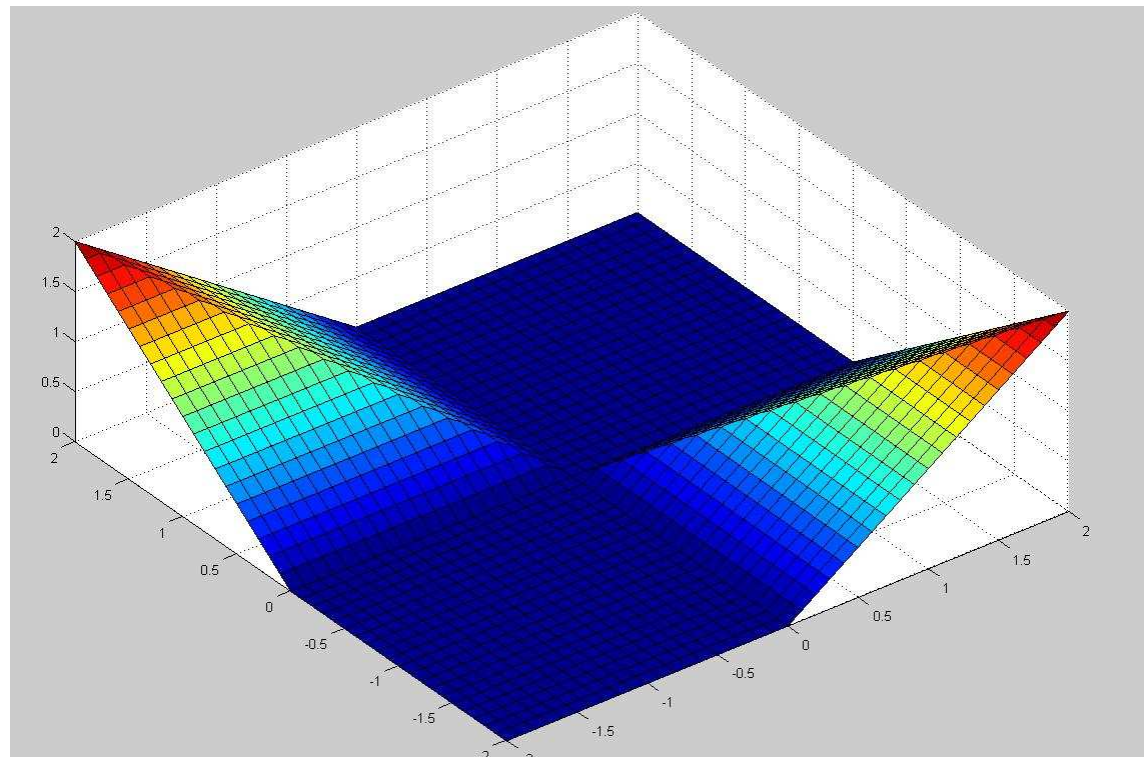
# Basket Option: k2

Let the underlying of the Basket option be X and Y

1. Payoff =  $(X + Y - K)^+$

For simplicity,  $K = 0$ :  $(X+Y)^+ \leq X^+ + Y^+$

So,  $X^+ + Y^+ - (X+Y)^+$



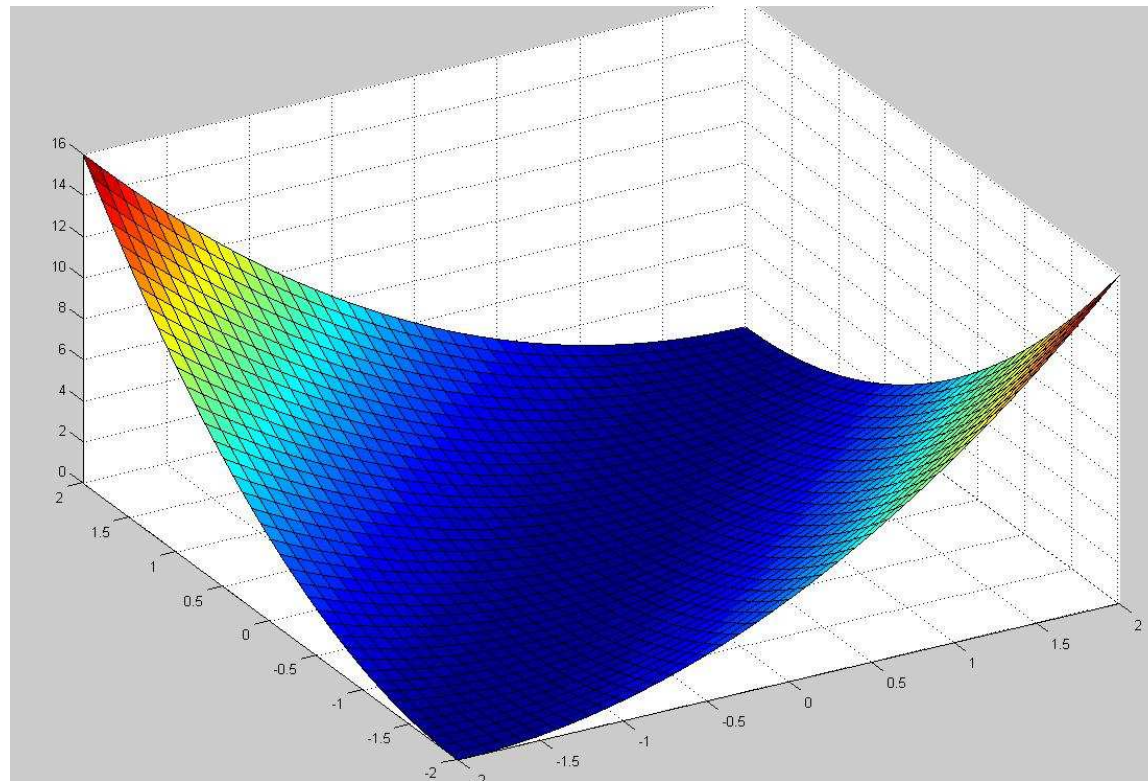
# Basket Parabola: k1

Let the underlying of the Basket option be X and Y

2. Payoff =  $(X + Y - K)^2$

For simplicity,  $K = 0$ :  $(X+Y)^2 \leq 2(X^2 + Y^2)$

So,  $2(X^2 + Y^2) - (X+Y)^2 = (X-Y)^2$



# Path Dependent Case

The same decomposition

$$g = LB + a + k_1 + k_2$$

still holds.

We make use of Functional Ito Formula

# Subfunctionals

$\Lambda$  functional



# LB and Functional Itô Formula

From Functional Ito Formula, if  $LB$  is smooth,

$$g(X_T) = LB(X_T)$$

$$= LB(X_0) + \int_0^T \Delta_x LB(X_u) dx_u + \frac{1}{2} \int_0^T \Delta_{xx} LB(X_u) d\langle x \rangle_u + \int_0^T \Delta_t LB(X_u) du$$

which gives the same decomposition  $g = LB + a + k_1 + k_2$

$$k_1(X_t) \equiv \frac{1}{2} \int_0^t \Delta_{xx} LB(X_u) d\langle x \rangle_u$$

$$k_2(X_t) \equiv \int_0^t \Delta_t LB(X_u) du$$

are non decreasing with disjoint supports

$$g = LB + a + k_1 + k_2$$

The claim  $k_1$  is  $k_1(X_T)$

The claim  $k_2$  is  $k_2(X_T)$

$\Delta_{xx}LB(X_t) > 0 \Leftrightarrow$  minimizing measure : freeze

If prices does not freeze, capture convexity (Parabola)

$\Delta_tLB(X_t) > 0 \Leftrightarrow$  minimizing measure : jump

If prices does not jump, capture time value (Range accrual)

**CONCLUSION**

# Conclusion

- Itô calculus can be extended to functionals of price paths
- Price difference between 2 models can be computed
- We get a variational calculus on volatility surfaces
- It leads to a strike/maturity decomposition of the volatility risk of the full portfolio
- (Path dependent) Claims can be decomposed in a canonical way. It refines the Kramkov result and splits the increasing process in 2