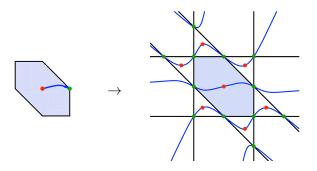
The Central Curve in Linear Programming

Cynthia Vinzant, U. Michigan



joint work with Jesús De Loera and Bernd Sturmfels



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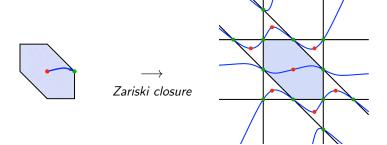
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We can use concepts from algebraic geometry and matroid theory to bound the total curvature of the central path.

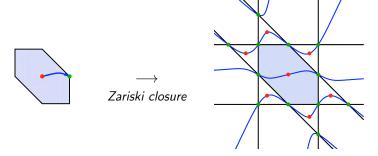
The Central Curve

The central curve \mathcal{C} is the Zariski closure of the central path. It contains the central paths of all polyhedra in the hyperplane arrangement $\{x_i = 0\}_{i=1,\dots,n} \subset \{A \cdot \mathbf{x} = \mathbf{b}\}.$



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Goal: Study the nice algebraic geometry of this curve and its applications to the linear program



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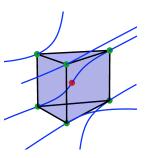
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Our contribution is to use results from algebraic geometry and matroid theory to find defining equations of the central curve and refine bounds on its degree and total curvature.

Outline

- Algebraic conditions for optimality
- o Degree of the curve (and other combinatorial data)
- Total curvature and the Gauss map
- Defining equations
- The primal-dual picture

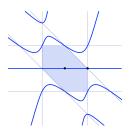


Some details

Here we assume that ...

- 1) A is a $d \times n$ matrix of rank-d (possibly very special), and
- 2) $\mathbf{c} \in \mathbb{R}^n$ and $\mathbf{b} \in \mathbb{R}^d$ are generic.

(This ensures that the central curve is irreducible and nonsingular.)



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where $\mathcal{L}_{A,c}^{-1}$ denotes the coordinate-wise reciprocal $\mathcal{L}_{A,c}$:

$$\mathcal{L}_{\mathsf{A},\mathbf{c}}^{-1} := \overline{\left\{ \; (u_1^{-1},\ldots,u_n^{-1}) \quad \mathsf{where} \quad (u_1,\ldots,u_n) \in \mathcal{L}_{\mathsf{A},\mathbf{c}} \;
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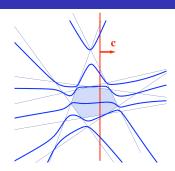
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Proposition. The central curve equals the intersection of the central sheet $\mathcal{L}_{A,\mathbf{c}}^{-1}$ with the affine space $\{A \cdot \mathbf{x} = \mathbf{b}\}$.



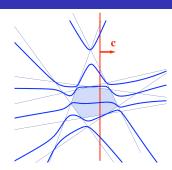
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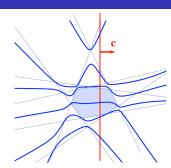


Observations:

- 1) There is exactly one point of $\mathcal{C} \cap \{\mathbf{c} \cdot \mathbf{x} = c_0\}$ in each bounded region of the induced hyperplane arrangement.
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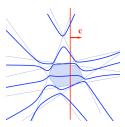
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Claim: The points $\mathcal{C} \cap \{\mathbf{c} \cdot \mathbf{x} = c_0\}$ are the analytic centers of the hyperplane arrangement $\{x_i = 0\}_{i \in [n]}$ in $\{A \cdot \mathbf{x} = \mathbf{b}, \ \mathbf{c} \cdot \mathbf{x} = c_0\}$.

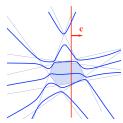


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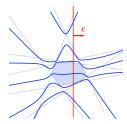
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Theorem: The number of bounded regions in hyperplane arrangement induced by $\{\mathbf{c} \cdot \mathbf{x} = c_0\}$ equals the degree of the central curve \mathcal{C} . Thus, $\deg(\mathcal{C}) \leq \binom{n-1}{d}$, with equality for generic A.

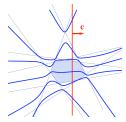


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For matroid enthusiasts, this number is the absolute value of the Möbius invariant of $\binom{A}{c}$.



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$$\Rightarrow$$
 deg $(\mathcal{C}) = \sum_{i=0}^d h_i$ and genus $(\mathcal{C}) = 1 - \sum_{j=0}^d (1-j)h_j$.



Total Curvature

Classic differential geometry: The total curvature of any real algebraic curve $\mathcal C$ in $\mathbb R^m$ is the arc length of its image under the Gauss map $\gamma:\mathcal C\to\mathbb S^{m-1}$. This quantity is bounded above by π times the degree of the projective Gauss curve in $\mathbb P^{m-1}$. That is,

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Theorem: The degree of the projective Gauss curve of the central curve C satisfies a bound in terms of matroid invariants:

$$\deg(\gamma(\mathcal{C})) \leq 2 \cdot \sum_{i=1}^{d} i \cdot h_i \leq 2 \cdot (n-d-1) \cdot \binom{n-1}{d-1}.$$



Proudfoot and Speyer (2006) also prove that the equations defining $\mathcal{L}_{A,\mathbf{c}}^{-1}$ are the homogeneous polynomials

$$\sum_{i \in \operatorname{supp}(v)} \frac{v_i}{v_i} \cdot \prod_{j \in \operatorname{supp}(v) \setminus \{i\}} x_j,$$

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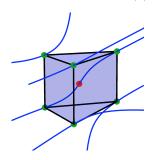
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$$(n = 5, d = 2)$$

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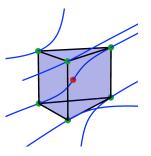


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Polynomials defining C:

$$\begin{array}{l} -2x_2x_3+x_1x_3+x_1x_2,\\ 4x_2x_4x_5-4x_1x_4x_5+x_1x_2x_5-x_1x_2x_4,\\ 4x_3x_4x_5-4x_1x_4x_5-x_1x_3x_5+x_1x_3x_4,\\ 4x_3x_4x_5-4x_2x_4x_5-2x_2x_3x_5+2x_2x_3x_4\\ x_1+x_2+x_3-3\\ x_4+x_5-2 \end{array}$$



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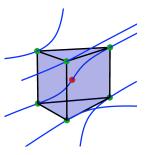
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$$h = (1, 2, 2) \Rightarrow \deg(\mathcal{C}) = 5$$
, total curvature $(\mathcal{C}) \leq 12\pi$



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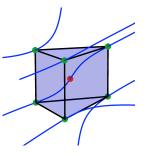
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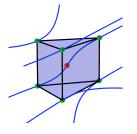


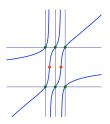
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Duality

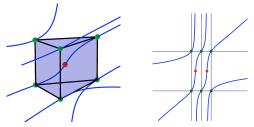
Dual LP: Minimize_{$\mathbf{s} \in \mathbb{R}^n$} $\mathbf{v}^T \mathbf{s}$ s.t. $B \cdot \mathbf{s} = \mathbf{w}$, $\mathbf{s} \ge 0$, where B = kernel(A), $A \cdot \mathbf{v} = \mathbf{b}$, and $B \cdot \mathbf{c} = \mathbf{w}$.





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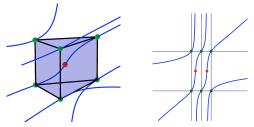
The primal-dual central path is cut out by the system of polynomial equations

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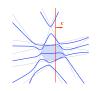


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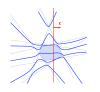
Examine $\lambda \to 0$ and $\lambda \to \infty$.







• What can be said about non-generic behavior?



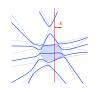


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Thanks and Happy Birthday to Mike!

