Which wave system is more turbulent: strongly or weakly nonlinear?

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Outline

Some (accepted?) statements:

- Strong turbulence ⇒ High nonlinearity
- Wave turbulence ⇒ small amplitudes & resonant N-wave interactions (plus quasi-resonant)

Evidence against these statements:

- Discovery of a new nonlinear transfer mechanism, stronger at intermediate values of nonlinearity
- Mechanism favours transfers towards non-resonant triads rather than quasi-resonant / resonant triads
- **Robust result**, backed up with Direct Numerical Simulations of nonlinear wave systems

Interaction Representation

• Equations for generic finite-sized 3-wave system:

$$\begin{aligned} \frac{\partial b_{k}}{\partial t} &= \sum_{k_{1},k_{2} \in \mathbb{Z}^{2}} V_{12,k}^{(1)} \, \delta(k - k_{1} - k_{2}) \, b_{k_{1}} \, b_{k_{2}} \, e^{i(\omega_{k} - \omega_{1} - \omega_{2})t} \\ &+ \sum_{k_{1},k_{2} \in \mathbb{Z}^{2}} V_{12,k}^{(2)} \, \delta(k + k_{1} - k_{2}) \, \overline{b_{k_{1}}} \, b_{k_{2}} \, e^{i(\omega_{k} + \omega_{1} - \omega_{2})t} \\ &+ \sum_{k_{1},k_{2} \in \mathbb{Z}^{2}} V_{12,k}^{(3)} \, \delta(k + k_{1} + k_{2}) \, \overline{b_{k_{1}}} \, \overline{b_{k_{2}}} \, e^{i(\omega_{k} + \omega_{1} + \omega_{2})t} \end{aligned}$$

Robust Instability Mechanism (1/3)

$$\frac{\partial b_{k}}{\partial t} = \sum_{k_{1},k_{2} \in \mathbb{Z}^{2}} V_{12,k}^{(1)} \,\delta(k - k_{1} - k_{2}) \,b_{k_{1}} \,b_{k_{2}} \,e^{i(\omega_{k} - \omega_{1} - \omega_{2})t}$$

+ etc ...

• Limit of small amplitudes $(|b_{k_j}| \ll 1, \text{ for all } j)$: phases $e^{i(\omega_k - \omega_1 - \omega_2)t}$ rotate faster than amplitudes b_{k_j} \Rightarrow each term in the RHS averages to zero at intermediate time scales

(Exception: exact resonances $\omega_k - \omega_1 - \omega_2 = 0$, but these are **irrelevant** for the mechanism of this talk)

Robust Instability Mechanism (2/3)

$$\frac{\partial b_{k}}{\partial t} = \sum_{k_{1},k_{2} \in \mathbb{Z}^{2}} V_{12,k}^{(1)} \,\delta(k - k_{1} - k_{2}) \,b_{k_{1}} \,b_{k_{2}} \,e^{i(\omega_{k} - \omega_{1} - \omega_{2})t}$$

+ etc ...

• Increase initial amplitudes b_{k_j} from infinitesimally small to finite values:

⇒ b_{k_j} 's nonlinear oscillation frequency, Γ , grows proportional to the amplitudes, until **resonance** occurs: <u>nonlinear</u> $\Gamma \sim \omega_k - \omega_1 - \omega_2$ <u>linear</u> ⇒ some terms in the RHS will contain **zero modes**

Robust Instability Mechanism (3/3)

$$\frac{\partial b_{k}}{\partial t} = \sum_{k_{1},k_{2} \in \mathbb{Z}^{2}} V_{12,k}^{(1)} \,\delta(k - k_{1} - k_{2}) \,b_{k_{1}} \,b_{k_{2}} \,e^{i(\omega_{k} - \omega_{1} - \omega_{2})t}$$

+ etc ...

- **Zero modes** in RHS:
- ⇒ Some amplitudes b_k grow linearly in time, without bound: $b_k(t) \sim c t$, c = const., even from zero i.c. ⇒ Far more robust than modulational instability!!!

• Can this mechanism be observed/modelled?

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Quantitative Studies of Strong Transfer Mechanism

- Finite-dimensional ODE model: Two triads connected via two common modes
 - Initial conditions: $b_k(0) = A b_k^{ref}(0)$, A: arbitrary const.
 - Energy flows from **source** triad to **target** triad
 - Physical mechanism and "linear-nonlinear" resonance
- Full direct numerical simulation of a PDE model
 - Initial conditions: $b_k(0) = A b_k^{ref}(0)$, A: arbitrary const.
 - Study turbulent cascades & transfer efficiency as a function of *A*

• Wave-vectors: $k_1 + k_2 = k_3$, $k_2 + k_3 = k_4$

• Frequency mismatches: $\delta_{s} = \omega_{1} + \omega_{2}$

$$\delta_{T} = \omega_{1} + \omega_{2} - \omega_{3}$$
 $\delta_{T} = \omega_{2} + \omega_{3} - \omega_{4}$

- Take $\delta_s = 0$ for simplicity (not essential)
- Equations of motion:

$$\begin{split} \dot{B}_{1} &= S_{1} B_{2}^{*} B_{3} \\ \dot{B}_{2} &= S_{2} B_{1}^{*} B_{3} + T_{1} B_{3}^{*} B_{4} e^{i\delta_{T} t} \\ \dot{B}_{3} &= S_{3} B_{1} B_{2} + T_{2} B_{2}^{*} B_{4} e^{i\delta_{T} t} \\ \dot{B}_{4} &= T_{3} B_{2} B_{3} e^{-i\delta_{T} t}, \qquad B_{j}(t) \in \mathbb{C} \end{split}$$

Initial Conditions:

$$B_1(0), B_2(0), B_3(0) \neq 0$$
 $B_4(0) = 0$

 k_3

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 $\dot{B}_1 = S_1 B_2^* B_3$ $\dot{B}_2 = S_2 B_1^* B_3 + T_1 B_3^* B_4 e^{i\delta_T t}$ $\dot{B}_3 = S_3 B_1 B_2 + T_2 B_2^* B_4 e^{i\delta_T t}$ $\dot{B}_{4} = T_{3} B_{2} B_{3} e^{-i\delta_{T} t}$ $B_i(t) \in \mathbb{C}$

- $B_1(0), B_2(0), B_3(0) \neq 0$ $B_4(0) = 0$
- 8-dimensional phase space
- 2 quadratic conservation laws & 2 slave variables ⇒ Effectively 4 degrees of freedom
- **Boundedness:** \exists positive-definite conservation law

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 k_4

$$\begin{split} \dot{B}_{1} &= S_{1} B_{2}^{*} B_{3} \\ \dot{B}_{2} &= S_{2} B_{1}^{*} B_{3} + T_{1} B_{3}^{*} B_{4} e^{i\delta_{T} t} \\ \dot{B}_{3} &= S_{3} B_{1} B_{2} + T_{2} B_{2}^{*} B_{4} e^{i\delta_{T} t} \\ \dot{B}_{4} &= T_{3} B_{2} B_{3} e^{-i\delta_{T} t}, \qquad B_{j}(t) \in \end{split}$$



• Assume $|B_4(t)|$ remains small for all times \Rightarrow system is further approximated by: $\dot{B}_1 = S_1 B_2^* B_3 \qquad \dot{B}_2 = S_2 B_1^* B_3 \qquad \dot{B}_3 = S_3 B_1 B_2$

$$\dot{B}_4 = T_3 B_2 B_3 e^{-i\delta_T t}$$

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• Assume $B_4(t)$ is small:

 $\dot{B}_1 = S_1 B_2^* B_3$ $\dot{B}_2 = S_2 B_1^* B_3$ $\dot{B}_3 = S_3 B_1 B_2$ $\dot{B}_4 = T_3 B_2 B_3 e^{-i\delta_T t}$

- B_1, B_2, B_3 satisfy the usual integrable triad equations
- $B_4(t)$ obtained by quadratures after B_2 , B_3 are known
- Triad: Jacobi Elliptic functions
 ⇒ bounded, quasi-periodic motion

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 $\dot{B}_{1} = S_{1} B_{2}^{*} B_{3}$ $\dot{B}_{2} = S_{2} B_{1}^{*} B_{3}$ $\dot{B}_{3} = S_{3} B_{1} B_{2}$ $\dot{B}_{4} = T_{3} B_{2} B_{3} e^{-i\delta_{T} t}$



- Amplitude-Phase representation: $B_j(t) = |B_j(t)|e^{i\varphi_j(t)}$
- $|B_1(t)|, |B_2(t)|, |B_3(t)|, \ \varphi(t) = \varphi_1(t) + \varphi_2(t) \varphi_3(t)$ are periodic functions with nonlinear frequency $\Gamma = \Gamma(|B_1(0)|, |B_2(0)|, |B_3(0)|; \ \varphi(0))$
- Homogeneity: $\Gamma(A x, A y, A z; \alpha) = A \Gamma(x, y, z; \alpha)$

 $\dot{B}_{1} = S_{1} B_{2}^{*} B_{3}$ $\dot{B}_{2} = S_{2} B_{1}^{*} B_{3}$ $\dot{B}_{3} = S_{3} B_{1} B_{2}$ $\dot{B}_{4} = T_{3} B_{2} B_{3} e^{-i\delta_{T} t}$



- $B_2(t) = |B_2(t)|e^{i(\varphi_2^{\text{per}}(t) + \Omega_2 t)}$ $B_3(t) = |B_3(t)|e^{i(\varphi_3^{\text{per}}(t) + \Omega_3 t)}$ (exact triad solutions)
- $|B_2(t)|, |B_3(t)|, \varphi_2^{\text{per}}(t), \varphi_3^{\text{per}}(t)$ are periodic: nonlinear frequency $\Gamma \sim$ amplitudes (homogeneity)
- Ω_2 , Ω_3 : precession frequencies, also ~ amplitudes

 $\dot{B}_{1} = S_{1} B_{2}^{*} B_{3}$ $\dot{B}_{2} = S_{2} B_{1}^{*} B_{3}$ $\dot{B}_{3} = S_{3} B_{1} B_{2}$ $\dot{B}_{4} = T_{3} B_{2} B_{3} e^{-i\delta_{T} t}$



- Solving by quadratures:
- $B_4(t) = T_3 \int_0^t f^{\text{per}}(\tau) e^{i(\Omega_2 + \Omega_3 \delta_T)\tau} d\tau$
- $f^{\text{per}}(t) \in \mathbb{C}$: periodic, nonlinear frequency Γ

⇒ Unbounded growth if resonance occurs: $n \Gamma + \Omega_2 + \Omega_3 - \delta_T = 0$, for some $n \in \mathbb{Z}$

 $\dot{B}_{1} = S_{1} B_{2}^{*} B_{3}$ $\dot{B}_{2} = S_{2} B_{1}^{*} B_{3}$ $\dot{B}_{3} = S_{3} B_{1} B_{2}$ $\dot{B}_{4} = T_{3} B_{2} B_{3} e^{-i\delta_{T} t}$



•
$$B_4(t) = T_3 \int_0^t f^{\text{per}}(\tau) e^{i(\Omega_2 + \Omega_3 - \delta_T)\tau} d\tau$$

• Fine-tuning initial conditions via simple re-scaling: $|B_j(0)| \rightarrow A |B_j(0)|$

$$\Rightarrow \text{Instability if } \mathbf{A} = A_n \left(\equiv \frac{\delta_T}{n \Gamma^{\text{ref}} + \Omega_2^{\text{ref}} + \Omega_3^{\text{ref}}} \right), \text{ for some } n \in \mathbb{Z}$$

ODE Model: Numerical Study



ODE Model: Numerical Study

Introduce an *ɛ*-family of systems:

$$\begin{split} \dot{B}_{1} &= S_{1} B_{2}^{*} B_{3} \\ \dot{B}_{2} &= S_{2} B_{1}^{*} B_{3} + \varepsilon T_{1} B_{3}^{*} B_{4} e^{i\delta_{T} t} \\ \dot{B}_{3} &= S_{3} B_{1} B_{2} + \varepsilon T_{2} B_{2}^{*} B_{4} e^{i\delta_{T} t} \\ \dot{B}_{4} &= T_{3} B_{2} B_{3} e^{-i\delta_{T} t} \\ \end{split}$$
where $0 \leq \varepsilon \leq 1$



 k_3

• $\varepsilon = 0$: Integrable system, with new resonant instability

- $\varepsilon = 1$: Full original system
- Study transfer efficiency as function of *A* & *ɛ*

Transfer Efficiency as function of A & ε



Transfer Efficiency as function of A & ε



Transfer Efficiency as function of A & ε





• Unstable periodic orbit





• Ratios (-1):(-2):(3)

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$$\frac{\partial}{\partial t} \left(\Delta \psi - \alpha^2 \psi \right) - \beta \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial x} \frac{\partial \Delta \psi}{\partial y} - \frac{\partial \psi}{\partial y} \frac{\partial \Delta \psi}{\partial x} = 0$$

Direct Numerical Simulations

- Pseudospectral
- Resolution 128 x 128
- Initial conditions at large scales, with an overall re-scaling factor *A* in front
- Dissipation at small scales: ENSTROPHY direct cascade

 $\frac{\partial}{\partial t} \left(\Delta \psi - \alpha^2 \psi \right) - \beta \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial x} \frac{\partial \Delta \psi}{\partial y} - \frac{\partial \psi}{\partial y} \frac{\partial \Delta \psi}{\partial x} = 0$

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 $\frac{\partial}{\partial t} \left(\Delta \psi - \alpha^2 \psi \right) - \beta \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial x} \frac{\partial \Delta \psi}{\partial y} - \frac{\partial \psi}{\partial y} \frac{\partial \Delta \psi}{\partial x} = 0$

Efficiency as a function of *A*



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 $\frac{\partial}{\partial t} \left(\Delta \psi - \alpha^2 \psi \right) - \beta \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial x} \frac{\partial \Delta \psi}{\partial y} - \frac{\partial \psi}{\partial y} \frac{\partial \Delta \psi}{\partial x} = 0$



VIDEOS

Conclusions

- Robust energy transfer mechanism towards nonresonant triads
- Analytically derived and verified numerically:
 - ODE "Atom" model
 - Direct numerical simulations of a full PDE model
- Implications of this mechanism:
 - Understanding turbulent cascades as a natural selection mechanism of triads
 - Yet another mechanism of rogue wave generation (triggered either by forcing or dissipation)
 - New paradigm for a complete theory of wave turbulence

Thank You!

• This Paper: ArXiv version <u>http://arxiv.org/abs/1305.5517</u>

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