

Parameter estimation of a tuberculosis model in a patchy environment in Cameroon

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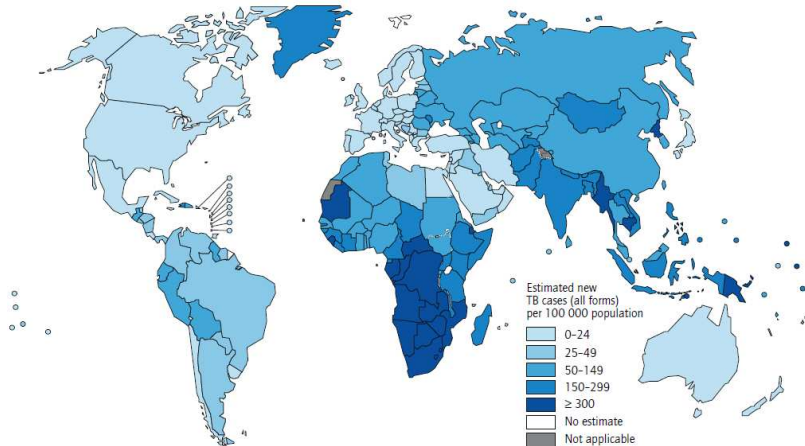
Joint work with S. Bowong, J. Kurths, P. Deuffhard



Biomat Conference 2013

Toronto, November 4, 2013

TB distribution 2012



[WHO, 2012]

TB Notification 2011

- ▶ New pulmonary TB Cases: **19868**
- ▶ Men 15-54 years old: **40%**
- ▶ Women 15-54 years old: **51.54%**
- ▶ HIV test positive: **38.91%**
- ▶ Newly enrolled in HIV cases: **36458**

TB Outcome 2010

- ▶ New pulmonary smear-positive cases cured: **63.97%**
- ▶ New pulmonary smear-positive cases died: **5.66%**
- ▶ Quitting treatment: **9.16%**

TB Estimations in 2011 (for 100,000 population)

- ▶ Estimated incidence of TB: **243**
- ▶ Estimated HIV in TB incidence: **76**
- ▶ Estimated number of deaths from TB : **24**
- ▶ Estimated Prevalence of deaths from TB : **299**



Source: [vidiani.com/maps]

Source: [who.int/tb/country/en/]

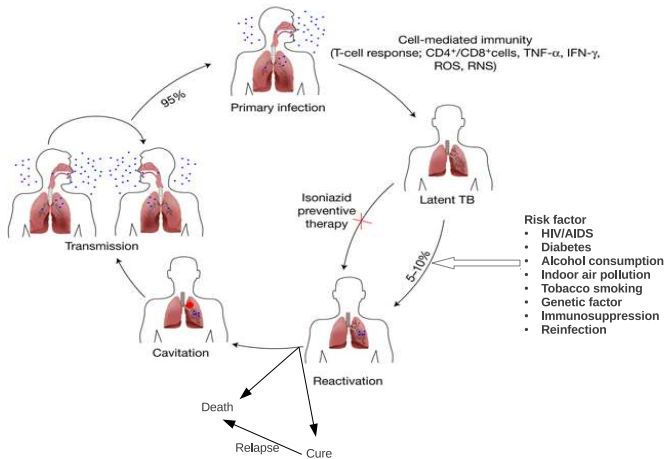
Aims

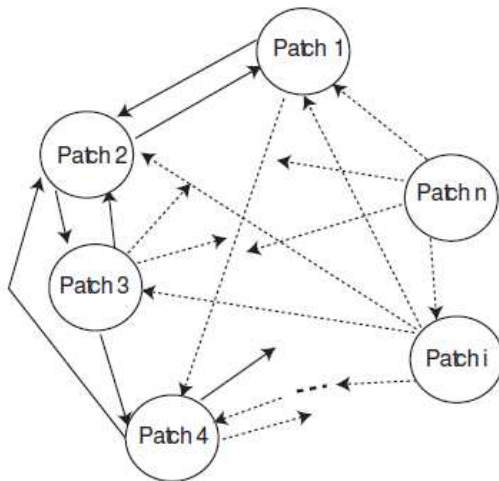
- ▶ A model for transmission dynamics of TB among Cameroon's regions
- ▶ Parameter identification of the model

What can we use such model for?

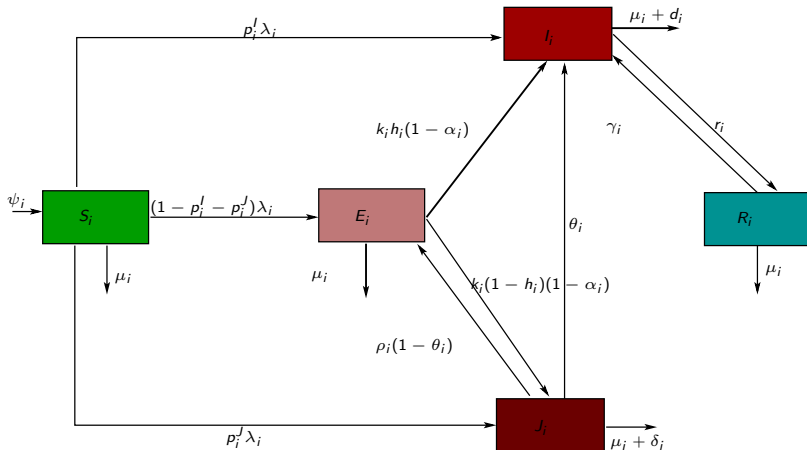
- ▶ Explore the role of undiagnosed infectious on TB transmission
- ▶ Identify key parameters on TB dynamics
- ▶ Determine sensitivities to changes in parameter values
- ▶ Estimate key parameters from measurable data

TB life cycle





Components and compartments



Force of infection: $\lambda_i = \beta_i^I \frac{I_i}{N_i} + \beta_i^J J_i,$

Model

$$\left\{ \begin{array}{l} \dot{S} = \psi - \lambda \cdot S - \mu S + \mathcal{M}S \\ \dot{E} = (\mathbf{1} - p^I - p^J) \cdot \lambda \cdot S + \rho \cdot (\mathbf{1} - \theta) J - A_E \cdot E + \mathcal{M}E \\ \dot{i} = p^I \cdot \lambda \cdot S + \theta \cdot J + \gamma \cdot R + h \cdot (\mathbf{1} - \alpha) \cdot k \cdot E - A_I \cdot I + \eta \mathcal{M}I \\ \dot{j} = p^J \cdot \lambda \cdot S + (\mathbf{1} - h) \cdot (\mathbf{1} - \alpha) \cdot k \cdot E - A_J \cdot J + \eta \mathcal{M}J \\ \dot{R} = r \cdot I - A_R \cdot R + \mathcal{M}R \end{array} \right.$$

$$\begin{cases} \dot{x} &= \varphi(x) + MS - \lambda(I)x, \\ \dot{y} &= \mathcal{F}(x, y) - \mathcal{V}(x, y), \end{cases}$$

where $x = S \in \mathbb{R}^n$ and $y = (E, I, J, R) \in \mathbb{R}^{4n}$.

$$\mathcal{R}_0 = \rho(\mathcal{F}_y(x_0, 0) \cdot (\mathcal{V}_y(x_0, 0))^{-1})$$

- ▶ **Basic reproduction ratio (\mathcal{R}_0)**: number of active cases one infectious generates on average over the course of its infectious period
- ▶ $\mathcal{R}_0 \leq 1$: TB dies out in the long run
- ▶ $\mathcal{R}_0 > 1$: TB persists and spread

- ▶ Model

$$\frac{d}{dt}y(t, \mathbf{p}) = f(t, y, \mathbf{p}), \quad t \geq 0$$

- ▶ Initial states vector $y(0, \mathbf{p}) = y_0 \in \mathbb{R}^N$
- ▶ Vector of parameters $\mathbf{p} \in \mathbb{R}^q$

$$\mathbf{S}_{ij}(t) := \left(\frac{\partial y_i}{\partial \mathbf{p}_j}(t) \right), \quad i = 1, \dots, N, \quad j = 1, \dots, q$$
$$\mathbf{S}' = f_y(y, \mathbf{p})\mathbf{S} + f_p(y, \mathbf{p}), \quad \mathbf{S}(t_0) = 0$$

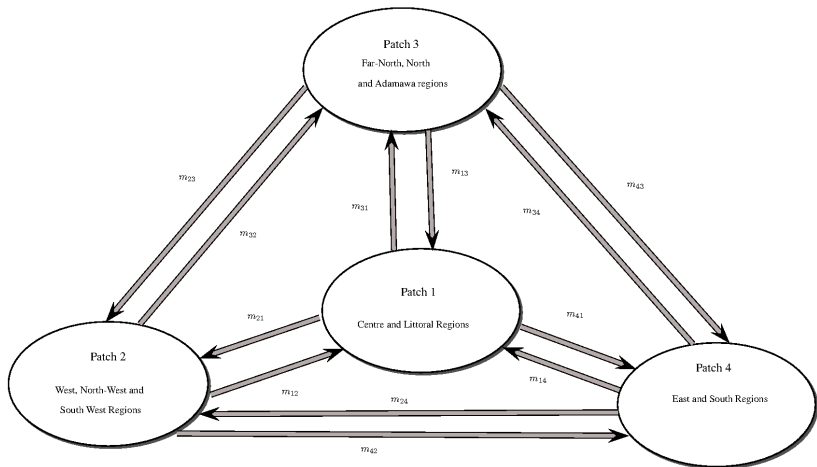
- ▶ Analysis of \mathbf{S} :

$$\mathbf{S}_j(t_k) := (\mathbf{S}_{1j}(t_k), \dots, \mathbf{S}_{nj}(t_k))^T$$

$$\mathbf{S}_{ij}(t_k) = \left(\frac{\partial y_{k_i}(t_k, \mathbf{p})}{\partial \mathbf{p}_j} \right), \quad k_i = 1, \dots, N$$

- ▶ Small sensitivity norms $\|\mathbf{S}_j\| = \|(\mathbf{S}_{ij}(t))\|$, $i = 1, \dots, m$ indicate a small sensitivity

Application on 4 patches



Sensitivity analysis (results)

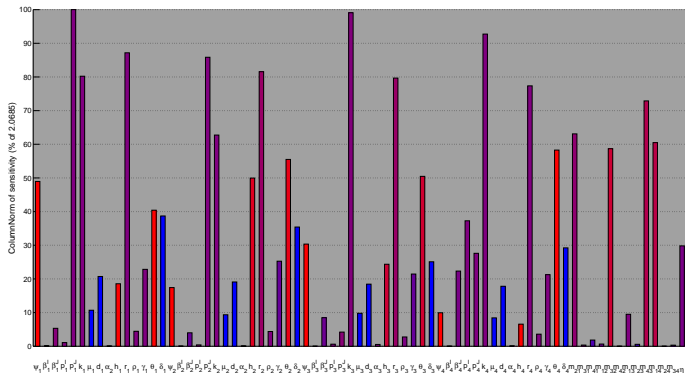
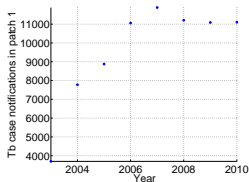
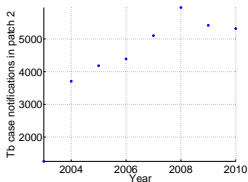


Figure: Sensitivity norms of unknown parameters

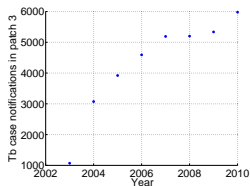
Data: number of diagnosed infectious



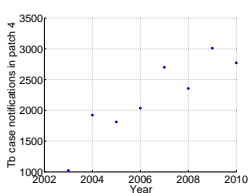
(a) I_1



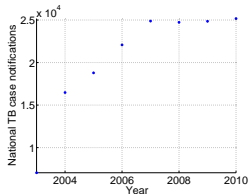
(b) I_2



(c) I_3

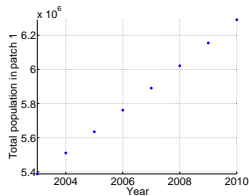


(d) I_4

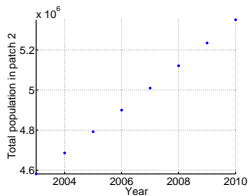


(e) I

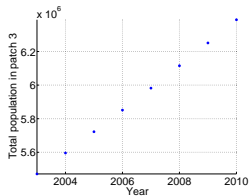
Data: total population



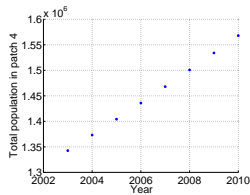
(f) N_1



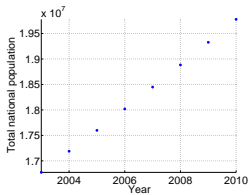
(g) N_2



(h) N_3



(i) N_4



(j) N

- ▶ Least squares formulation

$$\|F(\mathbf{p})\|_2^2 = \frac{1}{m} \sum_{j=1}^m \left\| \frac{y(\tau_j, \mathbf{p}) - z_j}{\delta z_j} \right\|_2^2 \rightarrow \min$$

- ▶ Data $z = (z_1, \dots, z_m)$
- ▶ δz_j : measurement accuracy of z_j
- ▶ The relative measurement accuracy is $\delta z_j = \varepsilon_z z_j$ with $\varepsilon_z = 10^{-1}$ to 10^{-3} in experiments

- ▶ Solution of the **nonlinear** least squares problem by a global **adaptive Gauss-Newton method**

$$\| F'(\mathbf{p}^k) \cdot \Delta \mathbf{p}^k + F(\mathbf{p}^k) \|_2^2 \rightarrow \min,$$
$$\mathbf{p}^{k+1} = \mathbf{p}^k + \lambda_k \Delta \mathbf{p}^k, \quad k = 0, 1, 2, \dots$$

[P. Deuffhard: *Newton Methods for Nonlinear Problems*, 2004]

- ▶ Sequence of **linear** least squares problems with $(m \times q)$ Jacobian matrix $F'(\mathbf{p})$
- ▶ A closer look of the expression of $F'(\mathbf{p})$ reveals that

$$F'(p) = \left(\frac{1}{\delta z_j} \right) \mathcal{S}, \quad \mathcal{S} = (\mathbf{S}(t_1), \dots, \mathbf{S}(t_m))$$

- ▶ **Good initial guess** required

- ▶ QR factorization with column pivoting

$$F'(\mathbf{p}^k)\Pi = QR, r_{11} \geq r_{22} \geq \dots \geq r_{qq}$$

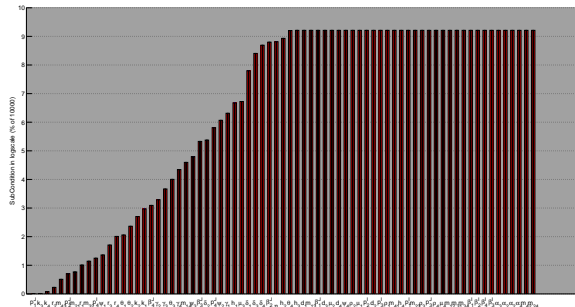
[P. Deuffhard and A. Hohmann,2003]

- ▶ The sub-condition of parameter \mathbf{p}_j is defined by

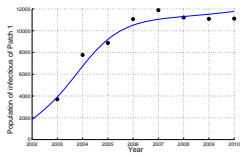
$$sc_j = \frac{r_{11}}{r_{jj}}$$

- ▶ Identifiable parameters: $\varepsilon_{\mathbf{p}_j} sc_j < 1$

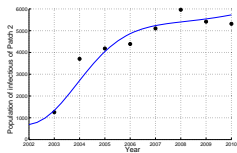
[P. Deuffhard and Sautter,1980]



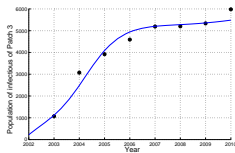
- ▶ Dependencies between parameters
- ▶ Only a few parameters can be identified



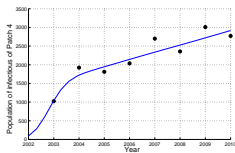
(k) I_1



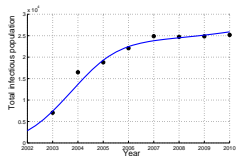
(l) I_2



(m) I_3

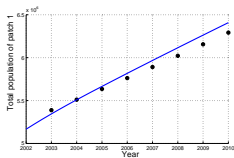


(n) I_4

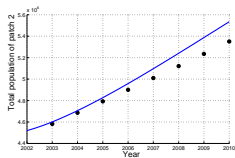


(o) I

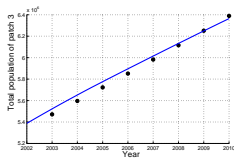
Numerical results (N)



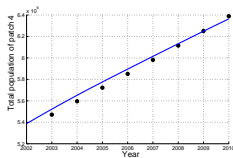
(p) N_1



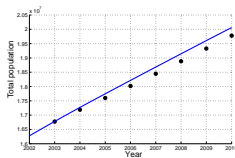
(q) N_2



(r) N_3

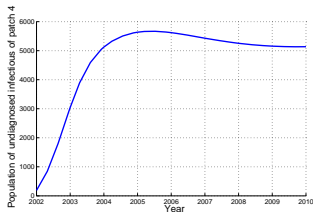
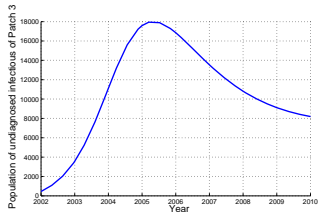
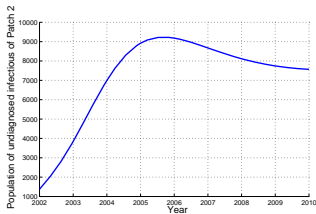
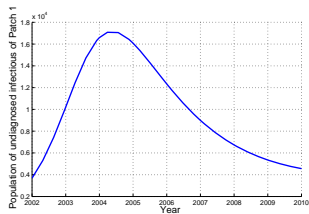


(s) N_4

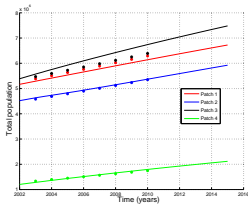
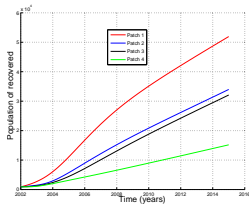
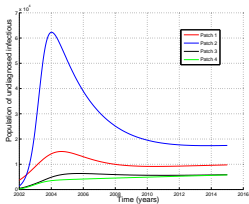
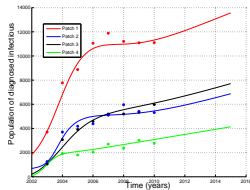
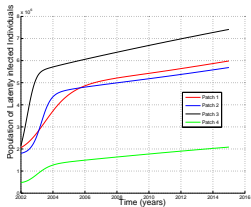
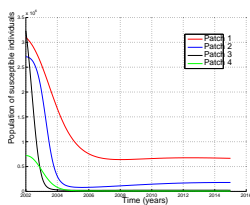


(t) N

Numerical results (J)



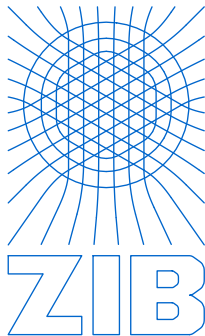
Numerical results (J)



- ▶ Prof. Peter Deuffhard
- ▶ Dr. Samuel Bowong
- ▶ Dr. Susanna Röblitz
- ▶ Dr. Martin Weiser
- ▶ Dr. Rainald Ehrig
- ▶ Prof. Jürgen Kurths



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